7. Office Procedures

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ABSTRACT

This paper outlines an effort to introduce automation into forms-oriented office procedures. The system allows its users to specify a set of operations on electronic forms. Actions are triggered automatically when certain events occur, for example, when forms or combinations of forms arrive at particular nodes in the network of stations. The actions deal with operations on forms. The paper discusses the facilities provided for the specification of form-oriented automatic procedures and sketches their implementation.

1. Introduction

Office *automation* implies that procedures followed in the office are understood, specified, translated into programs, and performed automatically by computers and communication devices. There are many problems, however, in accomplishing any degree of automation in the office.

The first difficulty is that most offices follow many procedures at the same time. Studies have indicated that thousands of different procedures are inherent in the operation of each office, and they are different among offices. In addition, the procedures are not always well understood and leave much flexibility for human intervention. It is a very difficult task to capture the procedures in any meaningful model which can later be used to guide the procedure specification.

The second difficulty is related to the nature of office procedures. Unlike regular data processing, office procedures have many exceptions. In fact, the whole office function seems like an exception-handling activity. Usual programming environments are very good at specifying repetitive procedures on vast amounts of data. They are not appropriate for specifying exceptions, especially when the exceptions are not well tabulated.

The third difficulty relates to the decision-oriented aspects of offices. There are many decisions in an office, even mundane ones, which involve vast amounts of knowledge and experience that are beyond the capabilities of any computer system. When office procedures are dependent on such decisions, they require human intervention. When human intervention is predominant, the automation aspects vanish. User interfaces and database access tools are more helpful than the specification of the procedures themselves. Only a very small part of the decision-oriented procedures can be fully automated.

Finally, office procedures are better understood at the local level. Individuals or offices know more about what they are doing than outsiders. The specification of their procedures may be feasible. When procedures specified at the local level are combined they may have difficulty achieving overall goals, or satisfying well-accepted constraints. Manual procedures are linked by humans who have much versatility in ironing out problems and incompatibilities. Automated office procedures do not show the same flexibility.

There are basically two design choices for a facility for office procedure specification. First, we need to decide what capabilities to provide in the specification. Second, we need to decide on the way of presenting this facility to the user. The generality of the specification is closely related to its goal. If it is mainly a requirements specification facility, without plans for implementation; it can be very general and powerful, for example, OSL [HaKu80]. If an implementation is desirable, then some of the generality needs to be sacrificed. For example, the specification language used in SCOOP is less general, but it has

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been implemented [Zism77].

There is also a choice of implementation environment. If the facility is implemented in LISP or some other powerful artificial intelligence tool, then a powerful specification environment can be put together with a reasonable effort. The problem of such an approach, however, is to achieve an acceptable level of performance on a small workstation. If the facility is implemented in a regular software environment, then the implementation effort is considerable. As a result, the facility is rather limited, but the performance is acceptable.

The second design choice relates to the user environment. If the specification facility is used by programmers, then it can resemble a programming language. If the specification facility is mainly geared to office workers with minimum programming expertise, then it should incorporate a very simple user interface. In the end, the size of the manual is as important as the functionality of the system.

In the rest of the paper, we outline an office procedure specification facility related to forms. Forms are used to specify procedures relating to form processing. Two kinds of procedures can be specified. Queries can be stated in relation to information on forms which are present in many different workstations. The query procedures are automatically executed in a distributed fashion and they return the cumulative results. The second kind of procedure deals with coordination of forms arriving at a single workstation. Depending on the specification, actions related to forms are automatically triggered and performed.

The specification and automation of forms-oriented procedures is realistic for two reasons. First, forms structure information in a manner which is easily amenable to computerization. Second, forms-oriented procedures are well understood, and carefully designed in an office environment. This design includes not only operations on forms at the local level but flow of forms among different office sites.

The specification facility is provided on top of OFS, a passive form-processing system. OFS is an electronic forms management system [Cheu79, Gibb79, Tsic82, TRGN82]. It provides an interface to MRS, a small, relational database system [Hudy78, Korn79, Ladd79]. OFS and MRS were written in C, within the UNIXTM operating system [KeRi78]. They have both been distributed widely to organizations.

An OFS system consists of a set of stations distributed over a number of machines in a network. Each user has a private set of forms residing in his station. A user may only manipulate those forms which he temporarily "owns", in the sense that they are part of his database. Communication and interaction between stations is achieved by allowing users to mail forms to one another.

A distinction is made in OFS between form types, form blanks, and form instances. A *form blank* is simply the form template used to display a form instance. A *form instance* corresponds to an actual filled form, represented as a tuple in the database of forms. Its fields may have values assigned to it, and it always has a unique key assigned at creation time by the system. A *form type* is the specification of a form blank and a set of field types. A *form file* is a relation used to store all forms of the same type, belonging to a station. The collection of form files for a station is a *form database*. Figures 1 and 2 show a form blank and form instance, respectively, for the form *type* called *order*. Note that some fields of the form instance need not have values associated with them. The key field must have a value which is automatically assigned by the system.

Form fields may be of six different types. Manual fields of type 1 may be inserted or modified at any time, type 2 fields may be inserted at any time but not modified, and type 3 fields must be inserted at form creation and never modified. Automatic fields of type 1 are key fields, always the first of a form; type 2 are date fields, and type 3 are signature fields, bearing the station's name if the preceding field is filled in.

Form operations are creation, selection, and modification. Forms may also be attached to *dossiers*. Dossiers are lists of forms which are not necessarily of the same form type, but which have something in common that the user wishes to capture.

Forms may not be destroyed, although they may be mailed to a "wastebasket station", which conceptually shreds the electronic form. The wastebasket station may in fact archive rather than erase a form, depending upon the needs of a particular application. Form instances are unique, and must always exist at exactly one location in the system. They are either in a form file or waiting in a mail tray. Forms may be mailed from one station to another. They must wait in a mail tray, and be explicitly retrieved in order to be placed in the receiving station's form file. Copies may be made of forms, but they are assigned a unique

ORDER FORM	Key :
Customer number : Customer name :	
Description : Item : Price : Quantity : Total :	

Figure	1: An	order	form	blank
0				

ORDER FORM	Key: 00001.00000
Customer number : Customer name :	354 CSRI
Description : Item : Price : Quantity : Total :	Office Forms System 254 200.00 2

Figure 2: An order form instance

key, consisting of the key of the original form together with a system-generated copy number distinguishing the copy from the original.

Form files may be accessed as a whole, using a relational MRS interface. However, in this case, no protection is provided against illegal operations such as destroying a form or creating a form with a key that is already in use. Therefore, the MRS interface is not meant to be used except by privileged users.

OFS is basically a passive system, that is, the user has to initiate every action. The only automatic form processing that OFS will do occurs if a form is mailed to a special automatic station. Such a station periodically reads its mail and submits the forms as input to an application program. These programs must be written so as to preserve the integrity of forms files. Consequently, the specification of an OFS automatic procedure requires a great deal of knowledge of the inner workings of OFS, and is therefore not intended for naive users. In the rest of the paper, we will discuss automatic procedures which have been implemented on top of OFS.

2. Distributed Queries

Some office activities may require information which is spread over more than one station. We will discuss how a station user specifies a query which is automatically performed on different stations, and how the result of a query is presented to the user.

As the first step in query specification the user selects the form type on which the query is to be performed. The form template is then displayed on the screen. A *query sketch* is next created by partially filling the template. This serves as an example, and informs the system of the kinds of forms qualifying for the query. This approach has been used in QBE, SBA, and OBE [deJo80, Zloo80]. The user may fill in zero or more fields of the template; values entered into the fields are interpreted as selection conditions. For example, if the user enters ">10" into a field, then all forms which satisfy the query will have values greater than 10 in this field. In addition to ">", one can also specify "<", or "=", etc., as well as a pattern match. Such a condition is known as a simple condition. For each field, it is possible to specify a field condition which is a disjunction of simple conditions. The forms that satisfy the query will satisfy the conjunction of all field conditions.

Once a query sketch has been created, the user next specifies the scope of the query. The allowable choices are as follows:

- *Local:* In this case the query is performed on the station database of the issuing station.
- *Group*: In this case the query is performed on all station databases on the same node as the issuing station.
- *Global*: In this case the query is performed on all databases in the network (this includes the mailboxes at the control node).

Explicit: In this case the user lists the station names of the station databases that are to be searched.

After specifying the scope, the query can be processed automatically. The results are stored in a temporary database belonging to the issuing station. This database contains *images* rather than objects; the objects themselves still reside in their respective station databases. A form image differs from a form, in that it is temporary and read-only. It is also invisible to other automated procedures that process forms. The tuples from this temporary database may be displayed by the station. When this occurs, the identification of the station database in which the form was found is also indicated.

Each query involves a single form type. It is not possible to directly specify operations involving more than one form type. However, arbitrarily complex multiple-type joins may be performed by first individually constructing complete temporary databases. The station user can then invoke a relational database system, and express his query (now over the local temporary database), using a high-level set-oriented relational query language.

M	IEETING ANNOUNCEMENT
To : From :	Key : Vassos Date :
Subject : Remarks :	*office automation* *database*
Meeting Date : Meeting Time : Location :	
Response :	

Figure 3: A query sketch

An example of a query sketch is shown in figure 3. This query will search for meeting announcements from "Vassos", on the subject "office automation" or "database". If this query is performed with a local scope, then the meeting announcements sent to the station user (or at least residing at his station) will be searched. If this query is performed with a global scope, then all meeting announcements in the system will be searched. By using the "Response" field of this message type, it is also possible to determine who has replied to the meeting announcement.

The strategy for processing a query automatically is determined by the scope of the query. Again we distinguish the following cases:

Local:

In this case the query manager is not used, and the station process itself performs the query on its station database.

Group:

In this case the station process sends the query to the query manager for the node. It then waits for an answer from the query manager.

Global/Explicit:

In this case the station process sends the query to a control node manager. The control node manager then passes the query to all query managers within the scope of the query. This may include the query manager on the control node. The various query managers perform the query on their nodes, and send the answer back to the control node manager. The control node manager assembles the answers in a temporary database, and may also perform the query on the mailbox if it is included in the query's scope. Finally, the control node manager sends the temporary database to the station process which issued the query.

Two problems arise in the automatic processing of queries: concurrency control of interfering global or local operations, and control of data movement due to mailing operations. Two algorithms, the centralized concurrency control algorithm and the centralized movement control algorithm [TRGN82], are used to circumvent these problems.

The concurrency control problem refers to the scheduling of operations which may conflict with queries. There are two such sources of interference, local updates and other queries. The system gives precedence to local updates. Stations are allowed to modify, create, or copy forms, even while queries are in progress. In addition, separate queries can operate concurrently. However, in this case, scheduling of the queries is required. For example, suppose data item X on station *i* initially has value a_1 , and then is changed, by a local update operation, to value a_2 . Similarly, on station *j*, the data item Y is changed from b_1 to b_2 . If we have two queries q_1 and q_2 , it is possible that q_1 will see X as a_1 and Y as b_2 , while q_2 will see X as a_2 and Y as b_1 . Whether we consider q_1 as occurring before or after q_2 , this result is inconsistent with the history of X and Y.

The source of this problem is that two distinct queries with overlapping scopes may be performed in different order on different nodes. This problem can be solved by having the control node manager serialize query requests. Each query, when accepted by the control node manager, is given a progressive sequence number: *Seq* (query). This is similar to the use of timestamps. However, since the *Seq* numbers are generated from a single node, any sequential ordering can be used. Queries are sent by the control node manager to the satellite nodes in this order. The network protocol ensures that the order of queries sent from one node to another is equal to the order received. Since there is a single query manager at each node, the queries are performed in this order, i.e., of their *Seq* numbers.

The movement of messages from one station database to another also introduces difficulties with query processing. In particular, the following pathological situations must be avoided.

The message *M* is missed by a query:

- 1. The query is performed on node *i* while the message *M* is on node *j*.
- 2. Message *M* is transferred to node *i*.
- 3. The query is performed on node *j*.

The message M is counted twice:

- 1. The query is performed on node *i* where it sees the message *M*.
- 2. Message *M* is transferred to node *j*.
- 3. The query is performed on node *j* where it again sees the message *M*.

We handle these problems by carefully orchestrating the order in which queries are performed. We also pay attention to the movements of forms in the mailboxes. A query is first performed on the station databases by the query managers, and then on the mailboxes by the control node manager. For messages that are transferred, it is necessary to keep track of the sequence number of the last query that has seen the message.

3. Form Procedures

The main automation facility deals with procedures that handle forms arriving at a station, and it is provided by the TLA system [Hogg81, Nier81]. (TLA stands for "Three Letter Acronym", and, unlike most acronyms, requires no apologies.) The user interface is presented in terms of objects with which the OFS user is already familiar. Specifying operations within a procedure corresponds closely to performing those operations within a manual system. A user who is editing an automatic forms procedure manipulates *sketches* of forms. *Sketches* are form-like objects representing the forms that the procedure will eventually manipulate. The same form template that OFS uses to display form instances is used quite differently in TLA, to describe preconditions and actions in office procedures. The specifications are non-procedural and have a simple syntax.

TLA does not assume any knowledge of the system state other than what is available to the user in his (or her) form file or mail tray. This corresponds to the notion in OFS that users can only manipulate the forms that they "own". Anything happening outside a user's own workstation does not concern him. The domain of automation is that of the individual workstation. The complexity of determining when to trigger a procedure is thereby considerably reduced.

An automatic procedure is meant to capture the notion of an office worker collecting forms at his desk until a "complete set" is compiled. He can then process the forms and file them or send them on their way. Processing of the collection of forms may cause forms to be modified or new forms to be added to the set. Reference tables and calculating tools are made available through an interface to a local library of application programs.

The other aspect of automation supplied by TLA is that of "smart forms", which automatically fill certain fields using previously filled-in fields as arguments. The domain here is that of the form alone, so triggering takes place whenever a form is created or modified.

There are two types of automatic fields. The first type is filled in only if all its arguments fields have values. The other type accepts null values, and is filled in even if some arguments fields are missing. Fields are initially filled in sequence. When an automatic field is reached, an application program written in a conventional programming language (usually C or the UNIXTM Shell) is executed. The output from this program is assigned to that field. If any of the argument fields is subsequently modified, the automatic fields which use it are also updated. Typical applications are arithmetic operations, such as sales tax calculations, or database queries, such as filling in a customer's address.

"Smarter forms" with fields that change value depending upon time conditions, the state of the system, or any other variable, were not implemented. Some "smarter form" problems can be solved with TLA's automatic procedures.

Automatic procedures have preconditions and actions, but no postconditions in the usual sense. Satisfying all preconditions guarantees the successful completion of all actions. There is only a very limited sense in which a procedure may "fail". For example, it may never be triggered, because missing forms do not arrive. Postconditions may be interpreted in terms of the preconditions of another procedure to which control of the forms is passed.

Automatic procedures run concurrently with the manual functions of the users. Conflicts can arise over the form manipulations. Forms being collected by an automatic procedure can be modified or shipped away manually. They can even be "stolen" by a competing automatic procedure. This implies that when a complete set of forms is gathered for a procedure, it has to be temporarily "removed" from the system. This operation safeguards the forms until they are processed.

4. Interface

The specification of an automatic procedure in TLA bears some resemblance to SBA and OBE [deJo80, Zloo80]. The precondition segment of a procedure bears a resemblance to a QBE query, with forms instead of tables as the data objects. In the simplest form of a TLA precondition, putting a value in a field of a precondition indicates that a form is to be found with a field matching that value. The action segment of the procedure is similar. The simplest operation is to assign to a field the value specified in an action.

The order in which forms needed by a procedure arrive is not important. The order in which actions are performed is not specified in detail. TLA merely ensures that the procedure be logically consistent. The specification is non-procedural. The user indicates what forms are to be collected, and what is to be done with them. He does not specify how they are to be collected or how the actions are to be performed.

Preconditions in TLA describe what, when and where. For each procedure there is a *working set* of forms. The working set may include forms that come only from certain workstations, forms local to the station specifying the procedure, or forms that have just been processed by another automatic procedure. One may also specify a procedure to run only at certain times or ranges of times.

A TLA procedure is a collection of "sketches". A *sketch* resembles a form, but is to be distinguished from form blanks, form types or form instances. A *precondition sketch* indicates a request to the system to find "a form that looks like this". An *action sketch* indicates a request to modify a form that has already been obtained. In either case, a sketch describes a form instance before or after processing by the procedure. The medium of specification of a sketch is the same form blank that is the template for the form instance being described. Actions and preconditions which do not refer to information found on a form are specified by *pseudo-sketches* of "pseudo-forms". For example, the condition that a procedure process only forms coming from user "john" must be indicated on a special *source pseudo-sketch*.

Sketches are used to capture the restrictions referring to values that appear on the face of the forms in the working set. *Local restrictions* are constant field values, sets or ranges of values, and relations between values of the fields on a given form. The local restrictions refer only to the values appearing on a single form in the working set. TLA tries to determine whether a given form satisfies the local restrictions (including the source condition) for a sketch in some automatic procedure. If it does, TLA notes the information and attempts to match that form with other forms to obtain a complete working set for that procedure.

Figure 4 is an example of a precondition sketch instructing TLA to watch for order forms requesting "Veeblefetzers". Since this information can be found right on the order form, it is a *local* precondition. A sample procedure including such a sketch might perform the single action of returning a form that says "We stopped making those things years ago!"

ORDER FORM	Key :
Customer number : Customer name :	
Description : Item : Price : Quantity : Total :	Veeblefetzers

Figure 4: A precondition sketch

Global restrictions on the working set of an automatic procedure are the join conditions between values of fields appearing on different forms. One expects all the forms in a procedure's working set to be linked by certain common field values. Matching field values are therefore probably adequate to model many applications of automatic procedures. However, simple inequality restrictions may also be specified.

Figure 5 shows how a link is made to find an *inv* form for the item requested on an *order* form. Each sketch in a procedure has a name assigned by the user. This name is a prefix to the field name. In this way a field of a different sketch can be referenced within a sketch. Note that one could alternatively have placed the restriction "=inv.item" in the item number field of the *order* precondition sketch.

INVENTORY RECORD	Key :
Item : Price : Quantity in stock :	=ord.item
Description :	

Figure 5: A global (join) precondition

We can also restrict the source of mail being processed by an automatic procedure. Suppose, for example, that the accounting department receives an order form from the order department. This may be interpreted as a request to forward a customer's address to the warehouse so that the order may be filled. If, however, the order form arrives from the warehouse, this may indicate that the order has gone through, and that an invoice should be mailed out. Figure 6 shows an origin pseudo-form sketch for such an application. Forms may thus be processed differently depending upon their point of origin. Alternatively, the special field *not* may be filled in to indicate that only forms coming from stations not listed in the pseudo-sketch should be processed by the procedure. The pseudo-station *me* is also available to indicate that forms must (or must not) come from within the station's own files.

ORIGIN PSEUDO-SKETCH Stations: ordering	NOT:

Figure 6: An origin pseudo-sketch

All form modification actions are indicated on action sketches. Every form manipulated by a forms procedure has a precondition sketch and an action sketch. Actions which do not concern themselves with field values must be expressed via pseudo-forms.

The action sketch indicates all insertions and updates to the form. The values to be inserted may be constant values, e.g., an authorization, copied field values, or possibly function calls to application programs. We distinguish, therefore, between the original and the updated values of any field. A field that must be copied to another form may itself be modified, and the wrong value must not be used. Furthermore, the function calls may access both the original and updated values of fields. In fact, the original value of a field will often be one of the arguments to a function call update to that field.

The action sketch in figure 7 illustrates several features. The *price* of an item is filled in by copying it from an *inv* form. A program called "mult" is called to calculate the total. Finally, the original value of *quantity* is accessed, whereas the updated value of *price* is used. Note that the symbols "#", "?" and "!" are used to respectively access functions, original field values, and updated field values. If none of these symbols is used, a constant string value is inserted.

ORDER FORM	Key :
Customer number : Customer name :	
Description : Item : Price : Quantity : Total :	?inv.price #mult !price ?quantity

Figure 7: An action sketch

Some analysis is needed to ensure that every updated file ultimately depends only upon values originally available on the working set of forms. It is clearly incorrect to update each of two fields by copying over the updated value of the other. Suppose that the *price* field of the order form were updated to "!inv.price" *and* the *price* field of the inventory form were updated to "!order.price". No order of execution could make sense of the request.

Field constraints must be obeyed. Procedures that create forms must fill in certain fields. Procedures that modify forms must only modify fields of an appropriate type. Implied actions must also be evaluated, if a procedure modifies or inserts a field which is an argument to an automatic field.

After all form modifications are completed, zero or more copies of each form are made. Each form or copy may then be left in the user's files, inserted into a dossier or shipped to another station. The mechanism used to specify these operations is the *destination* pseudo-sketch; an example is shown as figure 8. Copy 0 is the form manipulated by a procedure, and one additional destination pseudo-sketch is filled in for each copy of that form. The operations available are *leave, ship* and *dossier*. The first of these requires no *where* argument, but the others require the name of a station or a dossier, respectively. This may be given as a simple constant or a field function value, just as in action sketches.

DESTINATION PSEUDO-SKETCH	COPY: 0
Operation: ship	
Where: accounting	

Figure 8: Destination pseudo-sketch

A weak sort of postcondition is available by employing a function call to decide the operation, dossier name or shipping destination. General postconditions can only be achieved by cooperating form procedures that accept different cases of the working set of forms. Suppose, for example, that the processing of an order causes the quantity of an item in stock to dip below a certain acceptable level. We may wish, at this point, to send a memo to the manager, initiating an increase in the production of the item. The procedure which processes the order is incapable of *conditionally* producing this memo as a postcondition to inventory update. It could unconditionally produce such a memo and then functionally decide to mail it either to the manager or to a garbage collection station. A cleaner approach, though, is to have a separate procedure that searches for low inventory items, and then sends the memo.

With this approach, individual tasks are clearly identified. Automatic procedures are simple and completely devoid of control flow. Furthermore, the implementation is simpler, because postconditions correspond to separate procedures. The low inventory checker, for example, is only invoked when an inventory form is updated.

5. Implementation

An automatic forms procedure in TLA is specified by a collection of sketches, and consequently describes *what* is to be done rather than how to do it. The sketch representation is very convenient for the user. This format, however, is wholly unsuitable for implementation. The specification must be analyzed and translated for greater run-time efficiency.

We cannot predict when the forms required to trigger a forms procedure may arrive. The processing must, therefore, be broken into distinct parts. The specification, in terms of sketches, contains information of four basic kinds: local (form) constraints, global (working set) constraints, duplicate form types (so that one form is not used to match two sketches within a single working dossier), and actions. The execution of a forms procedure makes use of these four specifications at different stages. It is convenient to process these specifications at procedure definition time, and translate them into formats that require no further runtime analysis.

Suppose that TLA is notified of the availability of a form for automatic processing. It first checks whether the form matches the local conditions of any precondition sketch for that form type. The local conditions are comprised of the source restriction and the field constraints. If a form does not match the local constraints of any precondition sketch, then TLA assumes that no procedure is prepared to handle it. Suppose that a form does match the local constraints of one or more precondition sketches. That form is then a candidate for a working set for a number of procedures. It is immaterial whether or not a working set including that form is complete. There is always the possibility that at some time the missing forms of the working set could arrive.

The form instance in figure 10 matches the local condition of the precondition sketch in figure 9, i.e., *quantity*>0. There may not necessarily be a global match if there is no order form with the same item number. Even if there is an order form with the same item number, it may not satisfy the other constraints of its precondition sketch. Nevertheless, TLA notes that a local match has been made, and waits for the rest of the working set to arrive.

INVENTORY RECORD	Key :
Item : Price : Quantity in stock :	=ord.item >0
Description :	

Figure 9: Precondition sketch

INVENTORY RECORD	Key: 00001.00000
Item : Price : Quantity in stock :	465 16000.00 12
Description :	Workstation

Figure 10: Form instance matching local preconditions

TLA checks the local constraints of a form, records its findings, usually determines that the form does not complete a working set, and then waits for more forms to arrive. Further processing may not

occur for some time. All local constraints for forms of the same type are extracted from all procedures and stored in a common file. This file is opened to check the local constraints of a given form for all procedures.

After the local constraints have been matched for a form, TLA checks link conditions between the corresponding sketches of the procedure. The link conditions are stored in files by procedures. Suppose that, in the previous example, TLA found an order for item 0002. It would note that the link between the inventory and order form precondition sketches was satisfied by these two form instances. If the working set consisted of only these two forms, then the procedure actions would be performed. Otherwise, TLA would wait until forms were found to match the remaining links of the procedure.

Even if forms arrive together, the processing of the forms is sequential. TLA treats each form individually. A locking algorithm guarantees that two forms cannot be processed at once at a given workstation. Generally, forms will not arrive simultaneously. One can expect a considerable delay between the establishment of local constraints and the evaluation of links between forms.

Actions are performed only when a working set of forms has been compiled. Actions are stored in a separate file. TLA preprocesses procedures, to check the legality of actions and to determine a legal order of execution if one exists. No further run-time analysis is performed. Actions run to completion.

The example in figure 11 *implicitly* requires that *price* must first be copied from the inventory form before its value may be multiplied by the *quantity*. This establishes a legal order of actions for that sketch.

ORDER FORM	Key :
Customer number : Customer name :	
Description : Item : Price : Quantity : Total :	?inv.price #mult !price ?quantity

Figure 11: Ordering of actions

An admittedly unlikely case is captured in figure 12, which is triggered if TLA detects two inventory forms for a single item. Since there are two precondition sketches in the procedure, TLA assumes that they refer to two *different* forms in the working set. Otherwise, any inventory form would trivially satisfy both precondition sketches, and thus trigger the procedure. When the procedure is written, TLA notes immediately that two precondition sketches describe forms of the same type. It performs a key comparison of those forms in any working set identified to guarantee that they are not one and the same.

The TLA automatic procedure interpreter is triggered upon receipt of mail, form creation and form modification. Since the last two are the responsibility of the user, triggering in these cases involves only the spawning of a new interpreting process. In the first case, however, the interpreting process is initiated by the user who sent the mail.

Automatic procedures are meant to run regardless of whether the user to whom the corresponding station belongs ever signs on after the procedure is written. Mail in the system is routed through a host control node. The sending station sends a message to the host consisting of the contents of the form tuple and the name of the station which is to receive the mail. The host then stores the form, updates the receiving station's mail tray and sends a message to the recipient's station. At the recipient's station machine, the interpreting process is started. It communicates with the host, asking for images of each new form in the recipient's mailtray. The interpreter maintains files of form images for each form available for automatic processing. It deletes the images when the forms have been processed either automatically or by the user.

INVENTORY RECORD	Key :
Item : Price : Quantity in stock :	
Description :	

Precondition sketch inv1

INVENTORY RECORD	Key :
Item : Price : Quantity in stock :	=inv1.item
Description :	

Precondition sketch inv2

Figure 12: Duplicate form types in a procedure

The images are copies of the contents of each form for use by the interpreter alone, and are stored just as forms are stored. The user, however, has no access to the images as forms. They may not be modified, shipped away, or otherwise manipulated. They are not properly forms or copies of forms, but merely *images* of forms.

Mail may arrive while the interpreter is running. It, therefore, continues to process all mail until it discovers an empty tray, in a manner similar to that of the line printer deamon in UNIXTM. Only one interpreter may run at any time for a given station. In this way we eliminate interference problems between interpreters. A lock is placed on the running of the interpreter for a given station.

6. Sketch and Instance Graphs

The working set of a form procedure is abstracted in terms of a *sketch graph*, with the sketches as coloured vertices, and the matching conditions as edges in the graph. The form-gathering algorithm must find corresponding forms, and satisfy matching conditions of the sketch graph. An *instance graph* is associated with the forms retrieved. The interpreter tries to match the sketch graph in the instance graph.

Consider the precondition sketches in figure 13. A link between the account and order forms is established across the customer number. A link between the order and inventory forms is captured by *two* global conditions, one by item number and the other by quantity.

The corresponding sketch graph is shown in figure 14. Each sketch is represented by a labelled/coloured node. Each collection of global conditions between a pair of sketches is represented by a single edge.

When a form is passed to the interpreter, it first reads the file of local constraints for the forms of that type. Whenever a match is found, the interpreter notes which sketch of which procedure is matched by the form, and it enters a tuple consisting of the form type, the form key, the procedure and the sketch matched into a relation (called "NODE").

CUSTOMER ACC	OUNT Key:
Customer number: Credit rating: Balance:	=order.number

ORDER FORM	Key :
Customer number : Customer name :	
Description : Item : Price : Quantity : Total :	 ≤inv.quantity

INVENTORY RECORD	Key :
Item : Price : Quantity in stock :	=order.item
Description :	

Figure 13: Precondition sketches of a procedure



Figure 14: A sketch graph for a single procedure

The file of global constraints for the matched procedure is then read. For every link concerning the matched sketch, the system establishes whether the current form satisfies the join conditions with any of the forms previously recorded in the NODE relation. For every new link found, the system inserts a tuple into another relation called EDGE. EDGE records the form keys, types, sketch names, and the procedure name of every link established.

The NODE and EDGE relations describe an instance graph, with forms as vertices or nodes and links between them as edges. The vertices are coloured according to which sketch the form matches. If a form matches two or more distinct sketches in one or more procedures, it is multiply represented, once for each sketch. Procedure names partition the instance graph, since there can be no links between sketches of different procedures. For each partition, we wish to match the sketch graph that describes the working set of forms for that procedure. Nodes are assigned a unique colour for each sketch, and the corresponding colours are used in the instance graph. An instance of the sketch graph, then, must be found within the instance graph.

Figure 15 shows the instance graph for the procedures of figure 13. Forms have been found to match each of the precondition sketches of the procedure, but there is no complete working set. When a working set is found, it is processed and disappears from the instance graph. Note that most of the disconnected subgraphs of the instance graph are in fact subgraphs of the sketch graph. In the last case, however, there are two orders for a single item, and the relationship is not that simple. The first account form to complete either working set will complete the "copy" of the sketch graph to be found in the instance graph.



Figure 15: The instance graph for a procedure

The relationships between the forms in the working set of a form procedure are usually best expressed in terms of the join conditions. The sketch graph will generally be connected. The instance graph, however, will more often consist of several partially complete working sets of forms, and so will usually be disconnected.

If the join conditions imposed on the working set of forms are "nice", then each connected subgraph of the instance graph will also be a subgraph of the sketch graph. It is conceivable, however, that two forms satisfying a precondition sketch may each satisfy a join condition with a third form satisfying a second sketch in the same procedure. This anomaly will occur if the imposed join conditions are "not nice enough". In this case, the connected subgraphs of the instance graph are not as simply related to the sketch graph. Thus, establishing when a complete working set of forms has been compiled requires careful analysis.

When the system has finished processing a form, we know that the instance graph contains no copies of the sketch graph. If a copy of the sketch graph is identified, then a working set has been found, the procedure is executed, and the corresponding nodes and edges are purged from the instance graph. No more working sets remain. When a new form arrives, a working set of forms may be completed only if that new form is included. The analysis of the instance graph, then, need only concern the connected subgraphs that include nodes representing the new form.

Join conditions giving rise to sketch *trees* seem natural, since the "cheapest" description of the relationships between sketches would contain no cycles. If A is related to B and B is related to C, then one would hope not to find any other relationship holding between A and C. In practice, however, things may not be that simple. Join conditions might give rise to cycles, or even disconnected sketch graphs. Suppose that the warehouse, for example, has a single *value* form at its workstation, keeping track of the total dollar value of its stock. The procedures which update it would include a blank precondition sketch for a *value* form. Since there is no confusion about *which value* form is needed, there are no local or global conditions to be specified for it. The corresponding sketch graph in figure 16 is therefore disconnected.



Figure 16: A disconnected sketch graph

7. Graph-Chasing

The algorithm which searches the instance graph for a copy of the sketch graph employs a list of *potential working sets*. Initially there exists a single such set, containing only the key of the newly added form. Edges are traversed in the instance graph and keys are added to each set until all edges and nodes in the sketch graph have been checked.

We start at the node of the sketch graph corresponding to the new form. We traverse edges leading out from that node, and check off any new nodes that we reach. We may follow any previously untraversed edges leading from any node we have thus far reached. Edges will lead back to old nodes wherever cycles occur. If the sketch graph is disconnected, then the subgraph containing the first node will be traversed first. Edges not in that subgraph cannot lead from old nodes until an edge is traversed which checks off two new nodes.

The sketch and instance graphs in figure 17 will be used to illustrate the graph-chasing algorithm. The example contains both cycles and disjoint subgraphs.



Figure 17: Sample sketch and instance graphs

Sketches 3 and 5 are sketches for the same form type, but represent distinct forms in the procedure. The terms $\{a, b, c, \dots p\}$ are keys belonging to forms that match the local conditions of the sketch graph. Form *a*, for example, matches sketch 1. Edges in the instance graph represent joins. Forms *c* and *f*, for example, satisfy the global conditions between sketches 2 and 3.

The addition of form p results in the completion of the working set (a, c, f, h, p) where previously no complete working set existed. The algorithm presented here will identify this set of forms.

As we trace a path through the sketch graph, we try to mimic our actions nondeterministically in the instance graph. If we follow an edge in the sketch graph, we attempt to follow that edge in the instance graph for each set in our list. For each success, we add a new key to some set, and for each failure, we delete a set. Suppose that several edges may be traversed in the instance graph for a given edge of the

sketch graph. We then split the current set and add a new node for each copy. The closing of a cycle in the sketch corresponds conceptually to a select on the set list. In this way we ensure that links actually exist in the instance graph for the two relevant forms represented in each set.

Figure 18 describes the steps followed in locating the working set in our example. If at any point all working sets are eliminated, the algorithm halts, with no working set of forms identified.

potential					
working sets					
1	2	3	4	5	
				р	<i>p</i> is a new form matching sketch 5.
		f		р	From node 5 in the sketch graph we can reach node 3
		g		р	along edge $(3,5)$. The edges $((3,f),(5,p))$ and
					((3,g),(5,p)) in the instance graph are followed, and
					the potential working set is "split".
		C			the potential working set is spire.
	С	Ĵ		p	The edge $(2,3)$ is now followed, splitting the first set
	d	f		p	of the previous step
	d	g		p	of the previous step.
a	С	f		р	
b	d	f		р	Follow edge (1,2).
b	d	g		р	
a	С	f		p	Edge (2,5) completes a cycle. Perform a select on the
					sets resulting from the last step. Since $((2,d),(5,p))$ is
					not in the instance graph, two potential working sets
					are lost
<u> </u>		0			
a	С	f	h	p	All the edges in the sketch graph have been traversed.
					A form that matches sketch 4 must be added.
a	С	f	h	р	Check that form f differs from form p .

Figure 18: Finding a working set of forms

The sketch and instance graphs are described as follows: The sketch graph is G'(N', E'), where $N' = \{1, \dots, n\}$ is the set of colours and E' is a subset of $N' \times N'$ containing no (i, j) such that i = j. F is the set of form keys. The instance graph is G(N, E), where N is a subset of $N' \times F$ and E is a subset of $N \times N$. Furthermore, we adopt the convention that if x = (i, k) belongs to N, then x' = i and x'' = k, and if e = (x, y) belongs to E, then e' = (x', y').

In the example,

 $N' = \{1, 2, 3, 4, 5\}$ $E' = \{(1, 2), (2, 3), (3, 5), (2, 5)\},$ $F = \{a, b, c, d, f, g, h, l, m, p\},$ $N = \{(1, a), (1, b), \dots (5, p)\}, \text{ and}$ $E = \{((1, a), (2, c)), ((1, b), (2, d)), \dots ((2, c), (5, p))\}.$

We note, then, that for each x in N, x' must belong to N', and for each e in E, e' must belong to E' — i.e., nodes and edges in the instance graph correspond to nodes and edges of the sketch graph.

Suppose that finding a complete set of forms is equivalent to locating an instance of the sketch graph within the instance graph. We can express this as follows: We seek all subsets N'' of N such that

1.
$$\{x' | xmemberN''\} = N'$$

and

2. for each (i, j) in E', there exist x and y in N'' such that x' = i, y' = j and (x, y) belongs to E — i.e., for each node and edge of the sketch graph, there exist unique corresponding nodes and edges in the

spanning graph G'[N''].

In the example,

 $N'' = \{(1, a), (2, c), (3, f), (4, h), (5, p)\}.$

The algorithm for finding all such subsets N'' makes use of the knowledge that any working set of forms must include the most recently added node, say x. Furthermore, there are two checklists, *node* and *edge*, with slots for each element of N' and E', respectively. These record whether or not the edges and nodes have been inspected. All are initially set to false, and a set list, D, is initially set to empty. Each set has n slots to hold all the keys of any working set of forms found by the algorithm in figure 19.

```
Let x in n represent the newly added form.
Add a set to D, with slot x' set to x'': x must belong to the working set.
Set node[x'] to true: check off node[x'] of the sketch graph.
for each e = (i, j) in E' such that edge[e'] is false do
      if both node[i] and node[j] are false then
            for each set in D do
                   for each (y, z) in E where y' = i and z' = j do
                          copy the set
                          set slot i to y'', slot j to z''
                   end for
                   delete the original set
            end for
      else if exactly one of node[i] and node[j] is false then
            /* without loss of generality, node[i] */
             for each set in D do
                   for each (y, z) in E where y' = i and z' = j and y'' is already in slot i of the set do
                          copy the set
                          set slot j to z''
                   end for
                   delete the original set
            end for
      else if node[i] and node[j] are true then
            for each set in D where (y, z) is not in E and
                   y'' = 1, z'' = j do
                   delete the set
             end for
      end if
      set edge[e'] to true
      set node[i] to true
      set node [ j] to true
end for
```

Check that forms of the same type are different.

Figure 19: The graph-chasing algorithm

If D is empty when the algorithm is finished, then no working sets were found. If D is not empty, then the "first" set containing no duplicate keys is chosen as the working set.

The station's owner may attempt to move some of the forms in the working set while the interpreter is running. Each of the forms must therefore be set aside. Each form in the working set is deleted from the system so that the only copy is the interpreter's image of the form. If any of the forms cannot be found, then the interpreter restores all the forms retained thus far, and aborts the forms procedure.

If all the forms are successfully obtained, then the interpreter performs the set of actions. In the translation phase, the legality of actions, implied actions, and a legal order of actions have already been

determined.

Actions may "fail" if a string is too long to be inserted in a given field, or if a form is mailed to a nonexistent station. In the former case, TLA chooses to insert the null string by default, with the understanding that both humans and procedures are intelligent enough to interpret this, not as a value, but as a non-value. In the latter case, OFS (and consequently TLA) returns the mail to the sending workstation. Since TLA procedures are capable of recognizing the source of mail, it is presumed that this anomaly could be appropriately dealt with if a user felt it necessary.

8. Concluding Remarks

Our form-processing facility captures, in some sense, what is meant by an "automatic forms procedure". The context of OFS limits the range of possible actions upon forms. There are also many things that persons can do with OFS which have not been modelled in TLA. Automatic procedures, for example, are not smart enough to expect the timely return of a form which has been shipped away.

Form flow is determined by the particular configuration of procedures across the system. It is the responsibility of the users and an office administrator to model and analyze so that there are no undesirable side effects resulting from a particular combination of automatic procedures. Such analysis should be performed within a reasonable complexity bound, and it should be performed mechanically if at all possible (see the companion paper, "Message Flow Analysis").

The complexity of interpreting automatic procedures and form-gathering clearly depends on:

- 1. the size of the working set for a procedure,
- 2. the number of automatic procedures running at workstations, and
- 3. the number of form images "waiting" in the instance graphs of a workstation.

The complexity of identifying a sketch graph within the graph grows if the sketch graph is not merely a subgraph of the instance graph. Obviously, whatever factors contribute to this complexity must be considered in any "good office design". However, exactly what constitutes "good design", and to what extent it is feasible, is not easily established.

Partly completed working sets of forms may or may not have a particular meaning in terms of exceptions and errors. If forms are "missing" from a working set, the present forms may also be part of another working set. The missing forms would determine which procedure is to be activated. There is no way of telling which procedure forms are missing until they arrive. Missing forms may never arrive. There is no way of interpreting their absence as an error, except by placing some arbitrary time limit upon form-gathering.

Forms may satisfy partly completed working sets for a number of procedures. There is a need for some convenient way of displaying these sets. Users could interpret what is "missing", and possibly act on this information. Instance graphs could be quite complicated. Several partly completed sets may overlap in a single instance graph. A graphic display would present this information in a much better fashion than lists of form keys.

A simple feature that would increase user interaction with automatic procedures would be a function whose value is determined by the user. When the interpreter sees this function assigned to a field in an action sketch, it holds all the forms in the working set. It then notifies the user when he next signs on, and waits until the user makes a request to inspect the working set. At that point the user is allowed to assign a value to the field (or possibly abort the procedure), and then execution will resume.

Form flow between stations in TLA is determined by the interplay of automatic procedures. Flow of execution could be made more explicit by passing control between procedures in different stations. One should then also pass working sets of forms between procedures. In this way one could explicitly determine the order of operations. Procedures could then be called from other procedures without the need for form-gathering. Decision points could be modelled by branching rather than by a variety of similar working sets of forms. Which procedure is to be called could be decided by evaluating a function whose arguments are field values from the working set.

Many office automation systems have been strongly influenced by the SBA [deJo80] and OBE [Zloo80] systems and Officetalk [ElNu80]. The most noticeable exceptions are SCOOP [Zism77] and BDL

[HHKW77], which are, however, more office-systems programming languages than office workers' languages. TLA uses forms that are manipulated at workstations, like Officetalk; the non-procedural interface for defining procedures was in large part inspired by the work of deJong and Zloof. However, TLA takes a somewhat different approach from either.

A goal of the TLA project was to provide a facility for automating office procedures, which could be used by office workers, as opposed to computer professionals, with a minimum of training. As a result, there was an emphasis on providing familiar concepts and a highly uniform interface.

The form is a very familiar concept to all office workers. Therefore, the idea of a sketch is an easy one to teach. By contrast, the SBA notion of boxes is both useful and powerful. However, it has no analog in the office of today, and therefore requires a more expert office worker in its use.

In TLA, "conditions" (constraints) appear within a form itself. This reflects an underlying philosophy in the TLA project that the user interface should be as uniform as possible. There are no separate condition boxes attached to forms within the underlying manual system, and therefore there are no separate conditions attached to sketches. Information that absolutely cannot be obtained from the form fields (such as the source of the form) is specified using pseudo-sketches that resemble forms as closely as possible.

Our form specification facility, like its base systems, OFS and MRS, runs on very small computers. Most of the development was done for an LSI-11/23. It will essentially run on any $UNIX^{TM}$ -oriented work-station. This means that the hardware required for TLA is affordable by any office large enough to benefit from automation. At the same time, incremental growth can be easily achieved by adding additional machines, of a wide range of sizes, to a local net.

OFS, MRS, and TLA have been implemented on machines running under $UNIX^{TM}$. Compatibility with OFS was maintained in TLA. Changes to code, and the internal representation of an OFS system were mostly additions to modules and $UNIX^{TM}$ file directories. Where existing files and code were modified, compatibility was maintained, so that OFS would simply ignore the added TLA features. Conversion costs from an OFS system to one that supports TLA are negligible, and any TLA system can be run with the OFS subset. In essence, OFS, MRS and TLA are completely integrated.

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