

7. Optimization

Oscar Nierstrasz

Lecture notes courtesy Marcus Denker

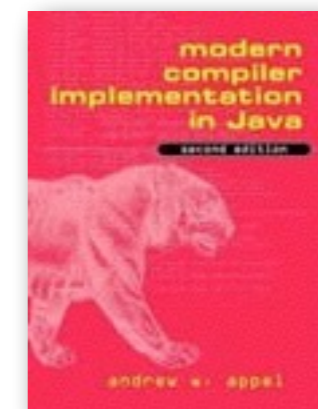
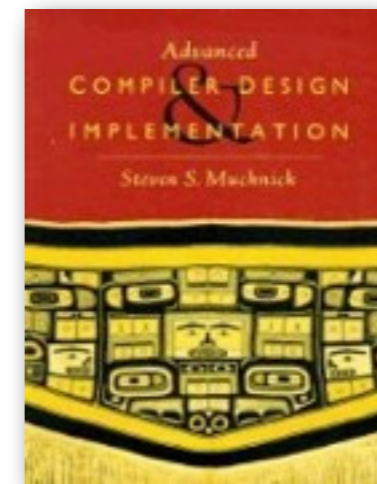
Roadmap

- > Introduction
- > Optimizations in the Back-end
- > The Optimizer
- > SSA Optimizations
- > Advanced Optimizations



Literature

- > Muchnick: *Advanced Compiler Design and Implementation*
—>600 pages on optimizations
- > Appel: *Modern Compiler Implementation in Java*
—*The basics*



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Optimization: The Idea

- > Transform the program to improve efficiency
- > **Performance**: faster execution
- > **Size**: smaller executable, smaller memory footprint

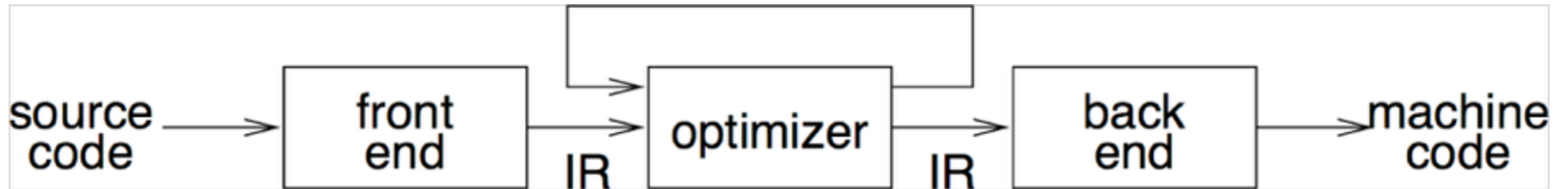
Tradeoffs:

- 1) **Performance vs. Size**
- 2) **Compilation speed and memory**

No Magic Bullet!

- > Rice (1953): *For every compiler there is a modified compiler that generates shorter code.*
- > **Proof:** Assume there is a compiler U that generates the shortest optimized program $\text{Opt}(P)$ for all P .
 - Assume P to be a program that does not stop and has no output
 - $\text{Opt}(P)$ will be `L1 goto L1`
 - Halting problem. Thus: U does not exist.
- > There will be always a better optimizer!
 - Job guarantee for compiler architects :-)

Optimization at many levels



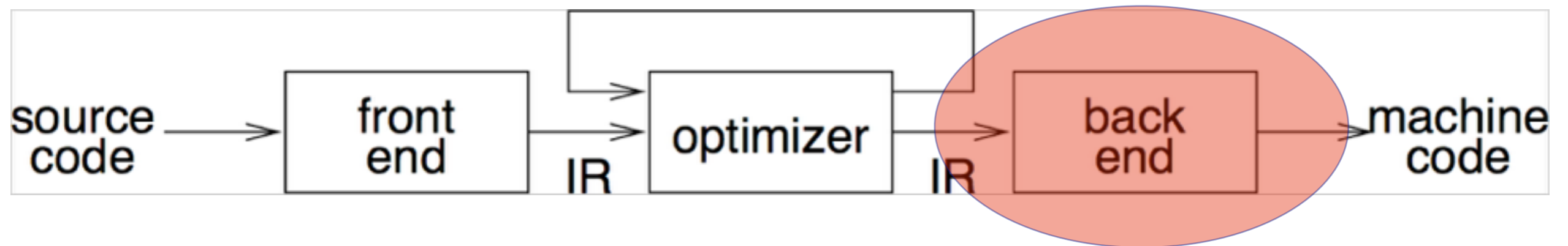
- > Optimizations both in the optimizer and back-end

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Optimizations in the Backend



- > Register Allocation
- > Instruction Selection
- > Peep-hole Optimization

Register Allocation

- > Processor has only finite amount of registers
 - Can be very small (x86)
- > Temporary variables
 - non-overlapping temporaries can share one register
- > Passing arguments via registers
- > Optimizing register allocation very important for good performance
 - Especially on x86

Instruction Selection

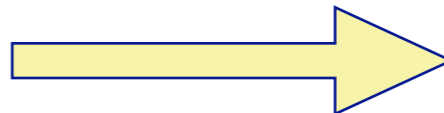
- > For every expression, there are many ways to realize them for a processor
- > Example: Multiplication*2 can be done by bit-shift

Instruction selection is a form of optimization

Peephole Optimization

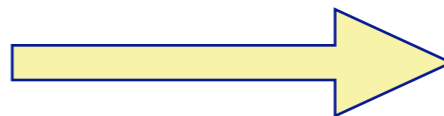
- > Simple local optimization
- > Look at code “through a hole”
 - replace sequences by known shorter ones
 - table pre-computed

```
store R,a;  
load a,R
```



```
store R,a;
```

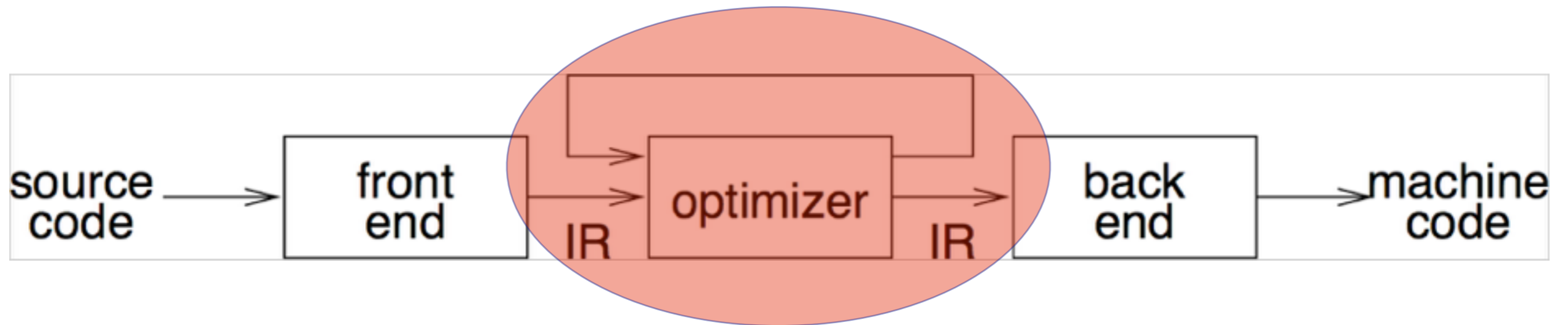
```
imul 2,R;
```



```
ashl 1,R;
```

Important when using simple instruction selection!

Optimization at many levels



Most optimization is done in a special phase

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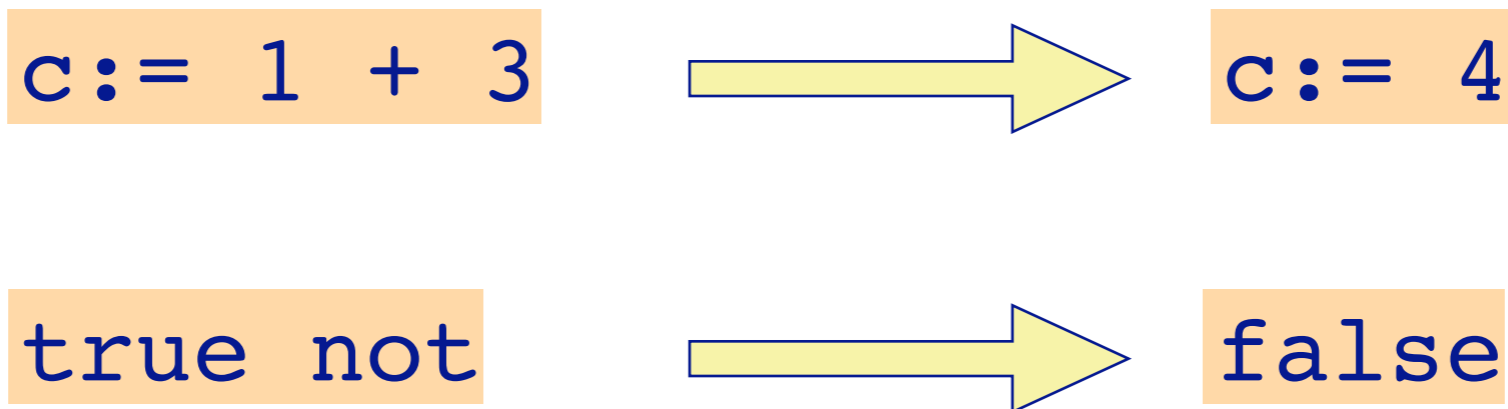


Examples for Optimizations

- > Constant Folding / Propagation
- > Copy Propagation
- > Algebraic Simplifications
- > Strength Reduction
- > Dead Code Elimination
 - Structure Simplifications
- > Loop Optimizations
- > Partial Redundancy Elimination
- > Code Inlining

Constant Folding

- > Evaluate constant expressions at compile time
- > Only possible when side-effect freeness guaranteed

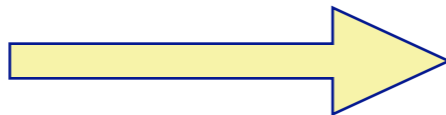


Caveat: Floats — implementation could be different between machines!

Constant Propagation

- > Variables that have constant value, e.g. $c := 3$
 - Later uses of c can be replaced by the constant
 - If no change of c between!

```
b := 3
c := 1 + b
d := b + c
```



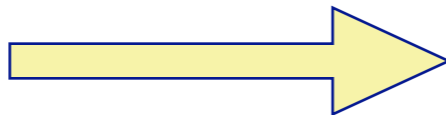
```
b := 3
c := 1 + 3
d := 3 + c
```

Analysis needed, as b can be assigned more than once!

Copy Propagation

- > for a statement $x := y$
- > replace later uses of x with y , if x and y have not been changed.

```
x := y  
c := 1 + x  
d := x + c
```

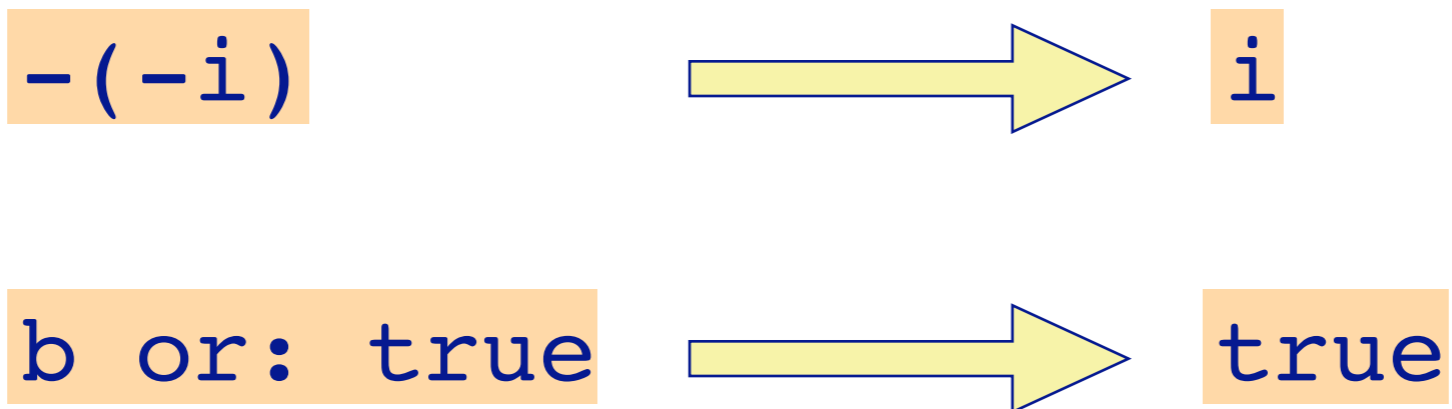


```
x := y  
c := 1 + y  
d := y + c
```

Analysis needed, as y and x can be assigned more than once!

Algebraic Simplifications

- > Use algebraic properties to simplify expressions

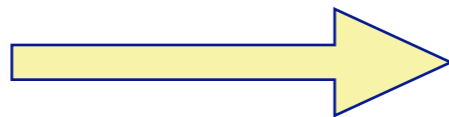


Important to simplify code for later optimizations

Strength Reduction

- > Replace expensive operations with simpler ones
- > Example: Multiplications replaced by additions

```
y := x * 2
```



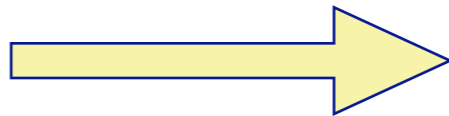
```
y := x + x
```

Peephole optimizations are often strength reductions

Dead Code

- > Remove *unnecessary* code
 - e.g. variables assigned but never read

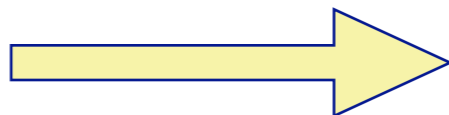
```
b := 3
c := 1 + 3
d := 3 + c
```



```
c := 1 + 3
d := 3 + c
```

- > Remove code never reached

```
if (false)
{a := 5}
```

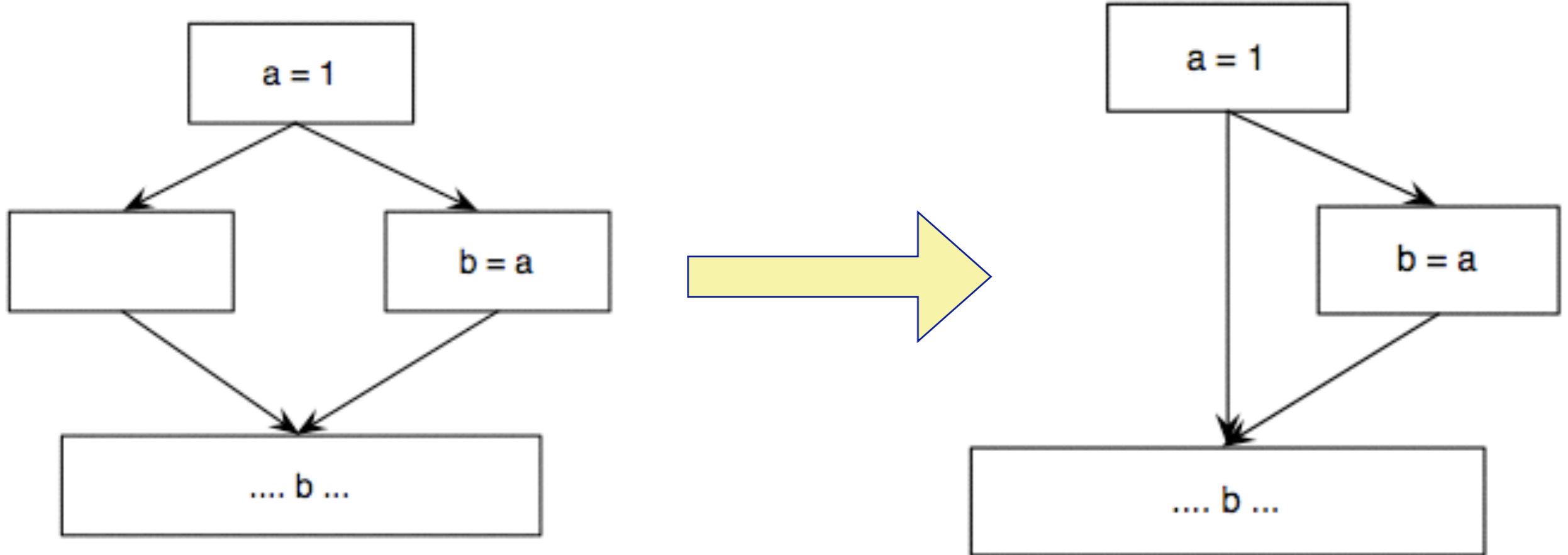


```
if (false)
{ }
```

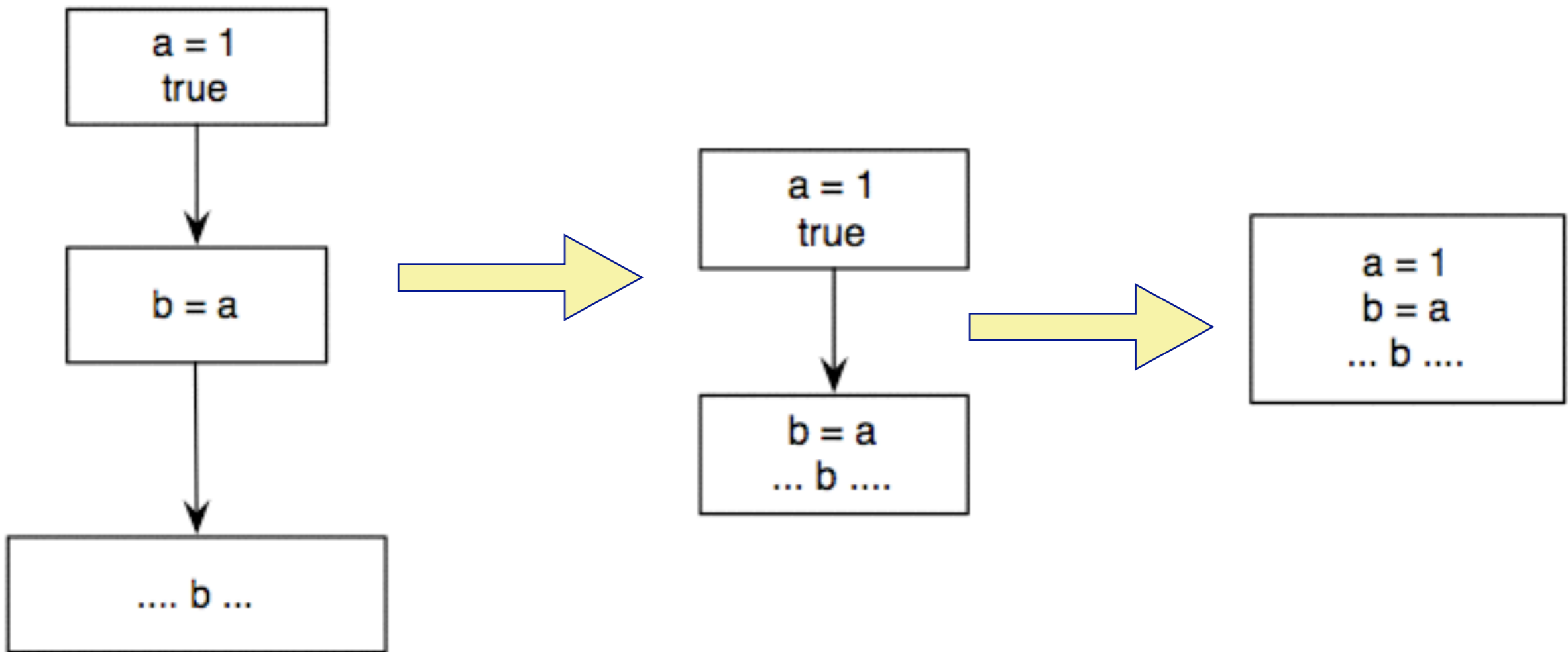
Simplify Structure

- > Similar to dead code: Simplify CFG Structure
 - Eg delete empty basic blocks, fuse basic blocks (next slides)
- > Optimizations will degenerate CFG
 - Needs to be cleaned to simplify further optimization!

Delete Empty Basic Blocks



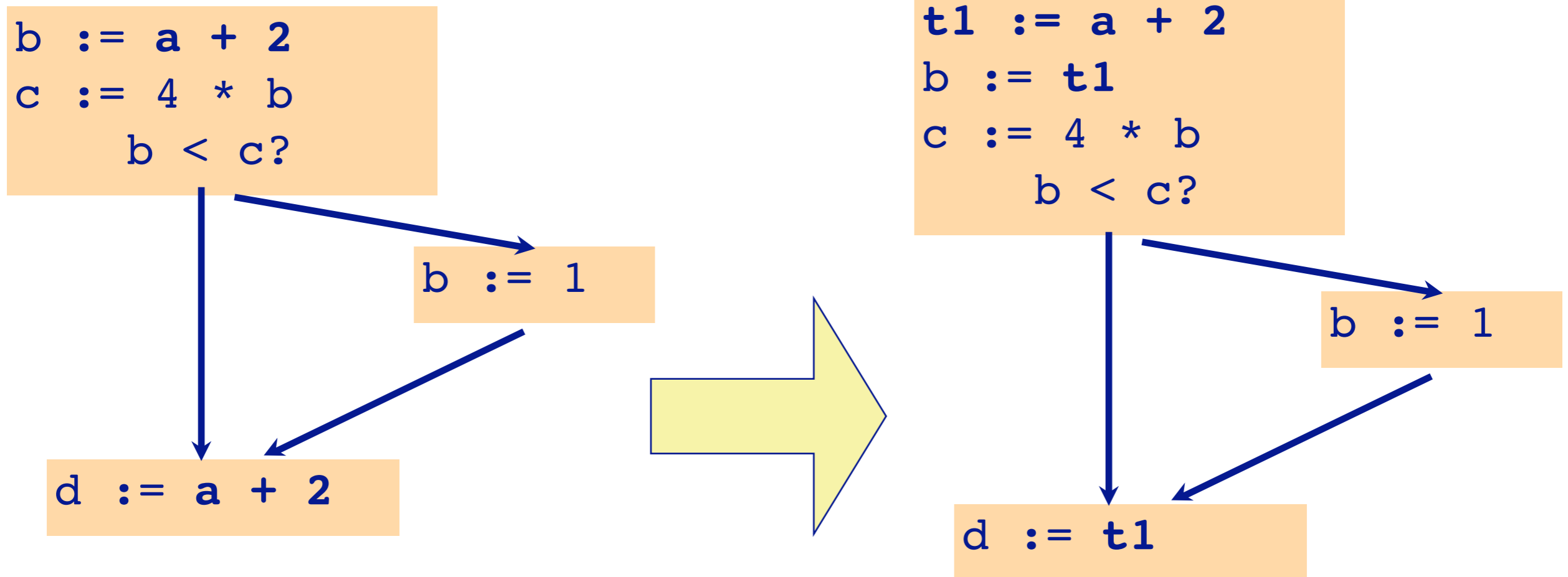
Fuse Basic Blocks



Common Subexpression Elimination (CSE)

- > **Common Subexpression:**
 - There is another occurrence of the expression whose evaluation always precedes this one
 - operands remain unchanged
- > **Local** (inside one basic block): When building IR
- > **Global** (complete flow-graph)

Example CSE



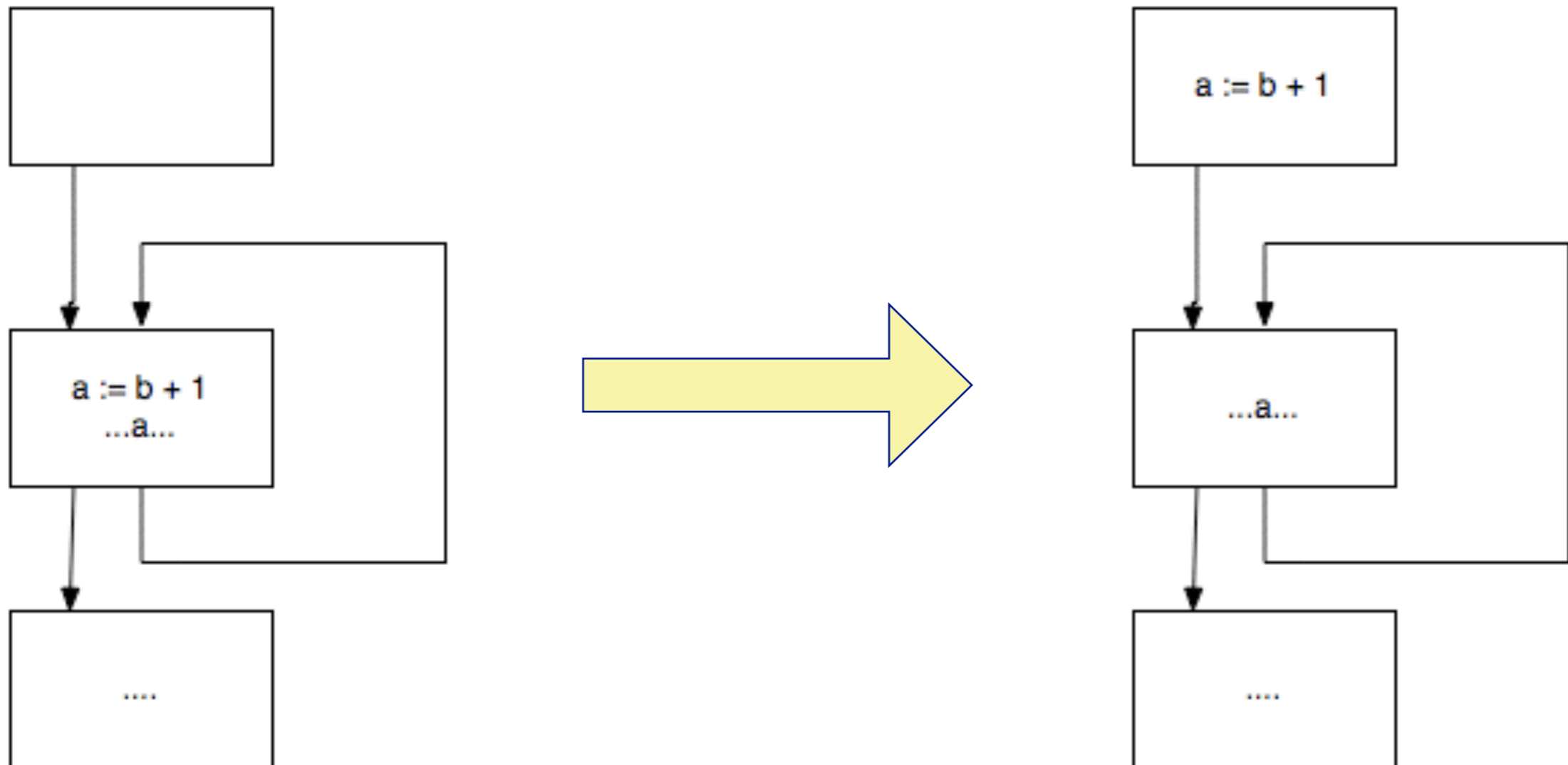
Loop Optimizations

- > Optimizing code in loops is important
 - often executed, large payoff
- > Various techniques
 - fission/fusion: split/combine loops to improve locality or reduce overhead
 - scheduling: run parts in multiple processors
 - unrolling: duplicate body several times to decrease test cost
 - loop-invariant code motion: move invariant code out of loop
 - ...

http://en.wikipedia.org/wiki/Loop_optimization

Loop Invariant Code Motion

- > Move expressions that are constant over all iterations out of the loop

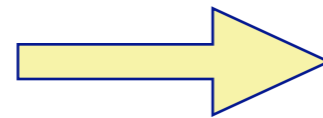


Induction Variable Optimizations

> Values of variables form an arithmetic progression

```
integer a(100)
do i = 1, 100
  a(i) = 202 - 2 * i
enddo
```

value assigned to *a*
decreases by 2



```
integer a(100)
t1 := 202
do i = 1, 100
  t1 := t1 - 2
  a(i) = t1
enddo
```

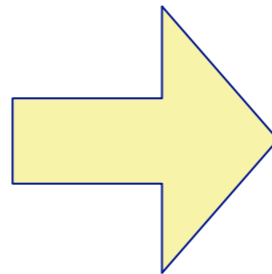
uses *Strength Reduction*

Partial Redundancy Elimination (PRE)

- > Combines multiple optimizations:
 - global common-subexpression elimination
 - loop-invariant code motion
- > **Partial Redundancy:** computation done more than once on some path in the flow-graph
- > PRE: insert and delete code to minimize redundancy.

Partial Redundancy Elimination

```
if (some_condition) {  
    // some code  
    y = x + 4;  
}  
else {  
    // other code  
}  
z = x + 4;
```



```
if (some_condition) {  
    // some code  
    t = x + 4;  
    y = t;  
}  
else {  
    // other code  
    t = x + 4;  
}  
z = t;
```

Code Inlining

- > All optimizations up to now were local to one procedure
- > **Problem:** procedures or functions are very short
 - Especially in good OO code!
- > **Solution:** Copy code of small procedures into the caller
 - OO: Polymorphic calls. Which method is called?

Example: Inlining

```
a := power2(b)
```

```
power2(x) {  
    return x*x  
}
```



```
a := b * b
```

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Recall: SSA

- > SSA: Static Single Assignment Form
- > **Definition:** Every variable is only assigned once

Properties

- > Definitions of variables (assignments) have a list of all uses
- > Variable uses (reads) point to the one definition
- > CFG of Basic Blocks

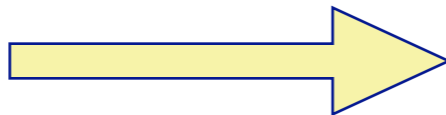
Examples: Optimization on SSA

- > We take three simple ones:
 - Constant Propagation
 - Copy Propagation
 - Simple Dead Code Elimination

Recall: Constant Propagation

- > Variables that have constant value, e.g. $c := 3$
 - Later uses of c can be replaced by the constant
 - If no change of c between!

```
b := 3
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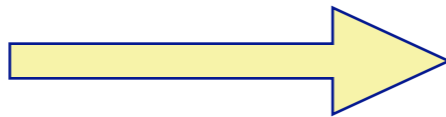
```
b := 3
c := 1 + 3
d := 3 + c
```

Analysis needed, as b can be assigned more than once!

Constant Propagation and SSA

- > Variables are assigned once
- > We know that we can replace all uses by the constant!

```
b1 := 3  
c1 := 1 + b1  
d1 := b1 + c1
```

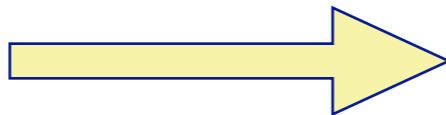


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Recall: Copy Propagation

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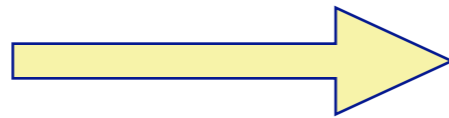
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x := y
c := 1 + y
d := y + c
```

Analysis needed, as y and x can be assigned more than once!

Copy Propagation and SSA

- > for a statement $x1 := y1$
- > replace later uses of $x1$ with $y1$

```
x1 := y1  
c1 := 1 + x1  
d1 := x1 + c1
```



```
x1 := y1  
c1 := 1 + y1  
d1 := y1 + c1
```

Dead Code Elimination and SSA

- > Variable is live if the list of uses is not empty.
- > Dead definitions can be deleted
—(If there is no side-effect)

```
b1 := 3  
c1 := 1 + 3  
d1 := 3 + c
```

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Profile-guided optimization

> Approach:

- Generate code,
- profile it in a typical scenario,
- then use that information to optimize it

> Problem:

- usage scenarios can change in deployment, there is no way to react to that as profile is generated at compile time.

Dynamic optimization

- > **Re-optimize at run time in the VM**
 - uses profile information gathered at run time
 - for both hardware and language VM
 - good way to exploit unused CPU cycles or unused CPUs (multi-core)

Multicore





- > Optimizing for using multiple processors
 - Auto parallelization
 - Very active area of research (again)

Iterative Process

- > There is no general “right” order of optimizations
- > One optimization generates new opportunities for a preceding one.
- > Optimization is an iterative process

Compile Time vs. Code Quality

What you should know!

-  *Why do we optimize programs?*
-  *Is there an optimal optimizer?*
-  *Where in a compiler does optimization happen?*
-  *Can you explain constant propagation?*

Can you answer these questions?

- ✎ What makes SSA suitable for optimization?*
- ✎ When is a definition of a variable live in SSA Form?*
- ✎ Why don't we just optimize on the AST?*
- ✎ Why do we need to optimize IR on different levels?*
- ✎ In which order do we run the different optimizations?*



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