

ESE

Einführung in Software Engineering

5. Software Validation

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Roadmap

- > Reliability, Failures and Faults
- > Fault Avoidance
- > Fault Tolerance
- > Verification and Validation
- > The Testing process
 - Black box testing
 - White box testing
 - Statistical testing

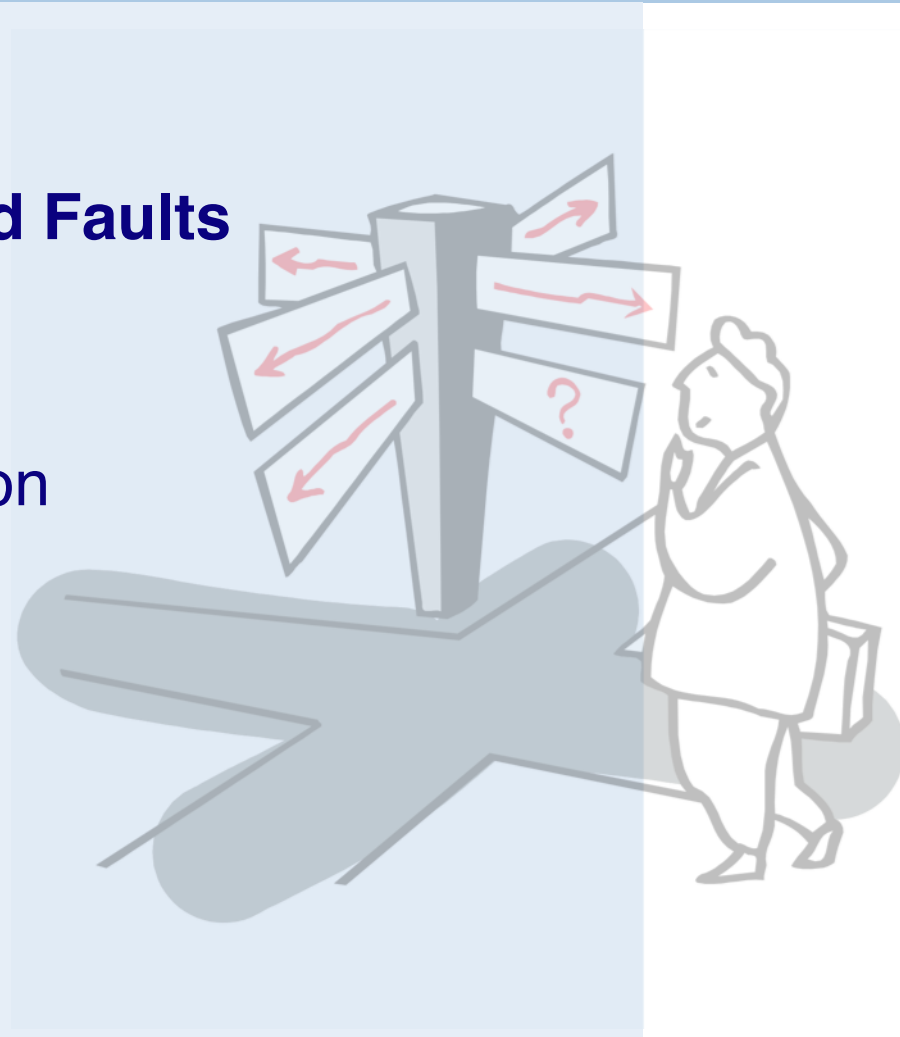


Source

- > *Software Engineering*, I. Sommerville, 7th Edn., 2004.

Roadmap

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Software Reliability, Failures and Faults

The reliability of a software system is a measure of how well it provides the services expected by its users, expressed in terms of software failures.

- > A software failure is an *execution event* where the software behaves in an unexpected or undesirable way.
- > A software fault is an *erroneous portion of a software system* which may cause failures to occur if it is run in a particular state, or with particular inputs.

Kinds of failures

<i>Failure class</i>	<i>Description</i>
<i>Transient</i>	Occurs only with <i>certain inputs</i>
<i>Permanent</i>	Occurs with <i>all inputs</i>
<i>Recoverable</i>	System can recover <i>without operator intervention</i>
<i>Unrecoverable</i>	Operator intervention is needed to recover from failure
<i>Non-corrupting</i>	Failure does not corrupt data
<i>Corrupting</i>	Failure corrupts system data

Programming for Reliability

Fault avoidance:

- > development techniques to *reduce the number of faults* in a system

Fault tolerance:

- > developing programs that will *operate despite the presence of faults*

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Fault Avoidance

Fault avoidance depends on:

1. A precise *system specification* (preferably formal)
2. Software design based on *information hiding and encapsulation*
3. Extensive *validation reviews* during the development process
4. An organizational *quality philosophy* to drive the software process
5. Planned *system testing* to expose faults and assess reliability

Common Sources of Software Faults

Several features of programming languages and systems are common sources of faults in software systems:

- > **Goto statements** and other unstructured programming constructs make programs *hard to understand, reason about and modify*.
 - Use structured programming constructs

- > **Floating point numbers** are *inherently imprecise* and may lead to invalid comparisons.
 - Fixed point numbers are safer for exact comparisons

- > **Pointers** are dangerous because of *aliasing*, and the risk of *corrupting memory*
 - Pointer usage should be confined to abstract data type implementations

Common Sources of Software Faults ...

- > **Parallelism** is dangerous because *timing differences* can affect overall program behaviour in *hard-to-predict* ways.
 - Minimize inter-process dependencies
- > **Recursion** can lead to *convoluted logic*, and may exhaust (stack) memory.
 - Use recursion in a disciplined way, within a controlled scope
- > **Interrupts** force transfer of control *independent of the current context*, and may cause a critical operation to be terminated.
 - Minimize the use of interrupts; prefer disciplined exceptions

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Fault Tolerance

A fault-tolerant system must carry out four activities:

1. **Failure detection:** *detect* that the system has reached a particular state or will result in a system failure
2. **Damage assessment:** *detect which parts* of the system state have been affected by the failure
3. **Fault recovery:** *restore the state* to a known, “safe” state (either by correcting the damaged state, or backing up to a previous, safe state)
4. **Fault repair:** *modify the system* so the fault does not recur (!)

Approaches to Fault Tolerance

N-version Programming:

Multiple versions of the software system are implemented *independently by different teams*.

The final system:

- > runs all the versions in *parallel*,
- > *compares* their results using a voting system, and
- > *rejects* inconsistent outputs.
(At least three versions should be available!)

Approaches to Fault Tolerance ...

Recovery Blocks:

A finer-grained approach in which a program unit contains a *test* to check for failure, and *alternative code* to back up and try in case of failure.

- > alternatives are executed in *sequence*, not in parallel
- > the *failure test is independent* (not by voting)

Defensive Programming

Failure detection:

- > Use the *type system* to ensure that variables do not get assigned invalid values.
- > Use *assertions* to detect failures and raise exceptions. Explicitly state and check all invariants for abstract data types, and pre- and post-conditions of procedures as assertions. Use exception handlers to recover from failures.
- > Use *damage assessment procedures*, where appropriate, to assess what parts of the state have been affected, before attempting to fix the damage.

Fault recovery:

- > *Backward recovery*: backup to a previous, consistent state
- > *Forward recovery*: make use of redundant information to reconstruct a consistent state from corrupted data

Examples

- > Concurrency control
 - Pessimistic (locking)
 - *Java synchronization; rcs*
 - Optimistic (check for conflict before commit)
 - *Cvs, subversion*
- > Fault recovery
 - Change logs (rollback and replay)
 - *Smalltalk image and changes*

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Verification and Validation

Verification:

- > Are we *building the product right*?
 - i.e., does it conform to specs?

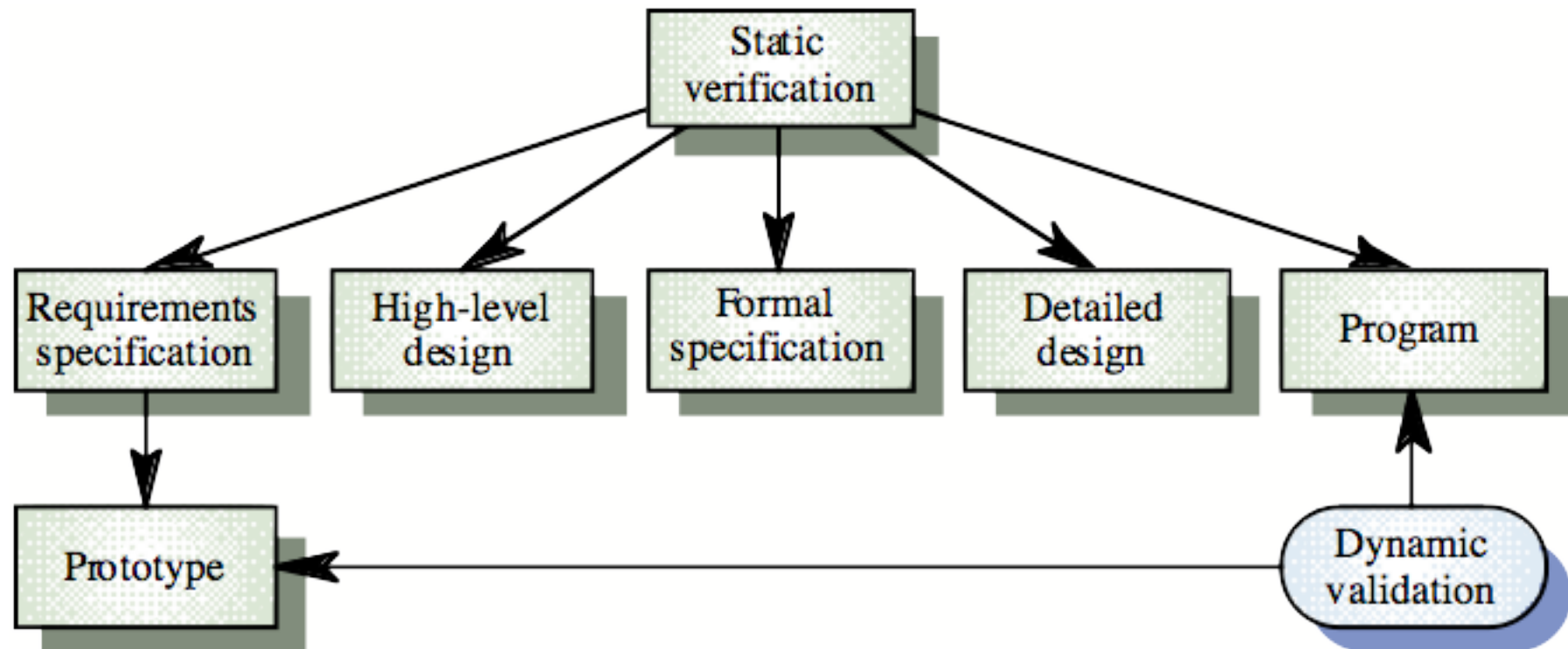
Validation:

- > Are we building the *right product*?
 - i.e., does it meet expectations?

Verification and Validation ...

Static techniques include program inspection, analysis and formal verification.

Dynamic techniques include statistical testing and defect testing ...



Static Verification

Program Inspections:

- > Small team systematically checks program code
- > Inspection checklist often drives this activity
 - e.g., “Are all invariants, pre- and post-conditions checked?” ...

Static Program Analysers:

- > Complements compiler to check for common errors
 - e.g., variable use before initialization

Mathematically-based Verification:

- > Use mathematical reasoning to demonstrate that program meets specification
 - e.g., that invariants are not violated, that loops terminate, etc.
 - e.g., model-checking tools

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The Testing Process

1. Unit testing:
 - Individual (stand-alone) *components* are tested to ensure that they operate correctly.
2. Module testing:
 - A collection of *related components* (a module) is tested as a group.
3. Sub-system testing:
 - The phase tests a *set of modules* integrated as a sub-system. Since the most common problems in large systems arise from sub-system interface mismatches, this phase focuses on testing these interfaces.

The Testing Process ...

4. System testing:
 - This phase concentrates on (i) detecting errors resulting from unexpected interactions between sub-systems, and (ii) validating that the complete systems fulfils functional and non-functional requirements.
5. Acceptance testing (alpha/beta testing):
 - The system is tested with *real* rather than simulated data.

Testing is iterative! Regression testing is performed when defects are repaired.

Regression testing

Regression testing means testing that everything that used to work *still works* after changes are made to the system!

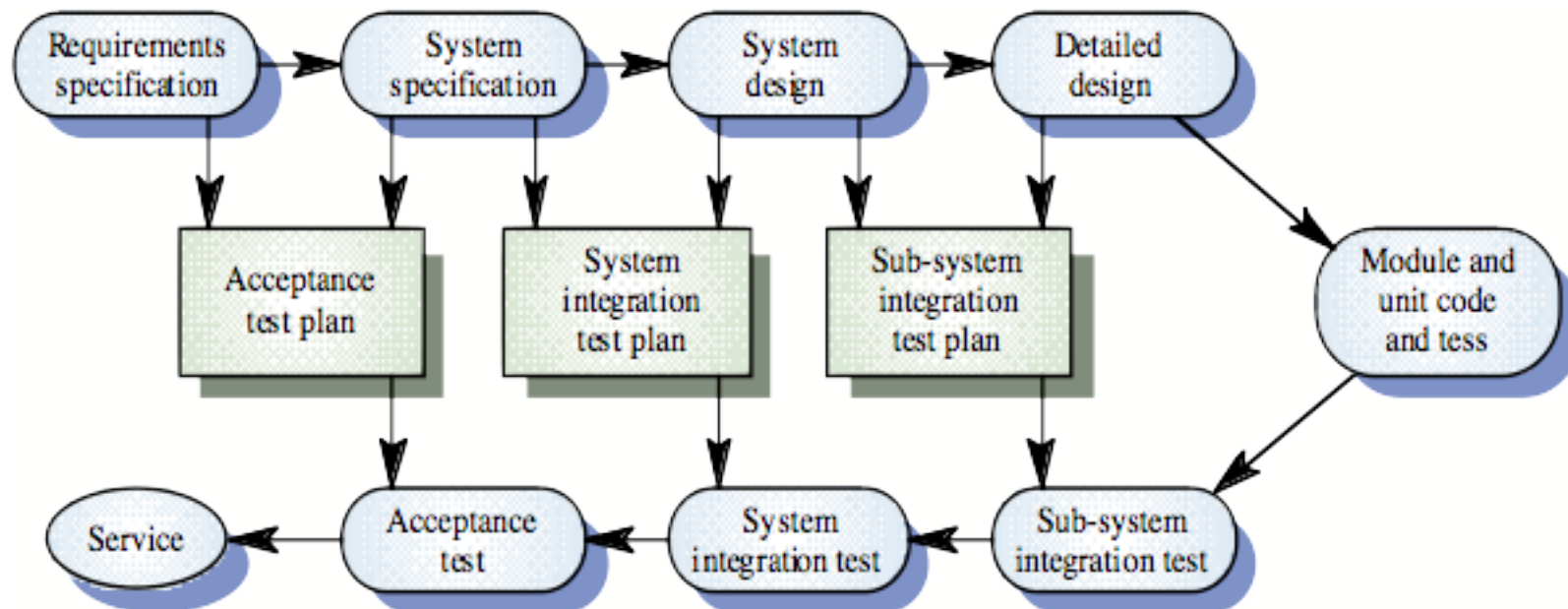
- > tests must be *deterministic* and *repeatable*

- > should test “all” functionality
 - every interface
 - all boundary situations
 - every feature
 - every line of code
 - everything that can conceivably go wrong!

It costs extra work to define tests up front, but they pay off in debugging & maintenance!

Test Planning

The preparation of the test plan should begin *when the system requirements are formulated*, and the plan should be developed in detail *as the software is designed*.



The plan should be *revised regularly*, and tests should be *repeated and extended* where the software process iterates.

Top-down Testing

- > *Start with sub-systems*, where modules are represented by “stubs”
- > Similarly test modules, representing functions as stubs
- > *Coding and testing* are carried out as a *single activity*
- > Design errors can be detected early on, avoiding expensive redesign
- > Always have a running (if limited) system!

BUT: may be impractical for stubs to simulate complex components

Bottom-up Testing

- > *Start by testing units* and modules
- > *Test drivers* must be written to exercise lower-level components
- > Works well for *reusable components* to be shared with other projects

BUT: pure bottom-up testing will not uncover *architectural faults* till late in the software process

Typically a combination of top-down and bottom-up testing is best.

Testing vs Correctness

- > “Program testing can be a very effective way to show the presence of bugs, but is hopelessly inadequate for showing their absence.”
 - *Edsger Dijkstra, The Humble Programmer, ACM Turing lecture, 1972*

Defect Testing

Tests are designed to *reveal the presence of defects* in the system.

Testing should, in principle, be exhaustive, but in practice can only be representative.

Test data are inputs devised to test the system.

Test cases are input/output specifications for a particular function being tested.

Defect Testing ...

Petschenik (1985) proposes:

1. “Testing a system’s *capabilities* is more important than testing its components.”
 - Choose test cases that will identify situations that may prevent users from doing their job.

2. “Testing *old capabilities* is more important than testing new capabilities.”
 - Always perform regression tests when the system is modified.

3. “Testing *typical situations* is more important than testing boundary value cases.”
 - If resources are limited, focus on typical usage patterns.

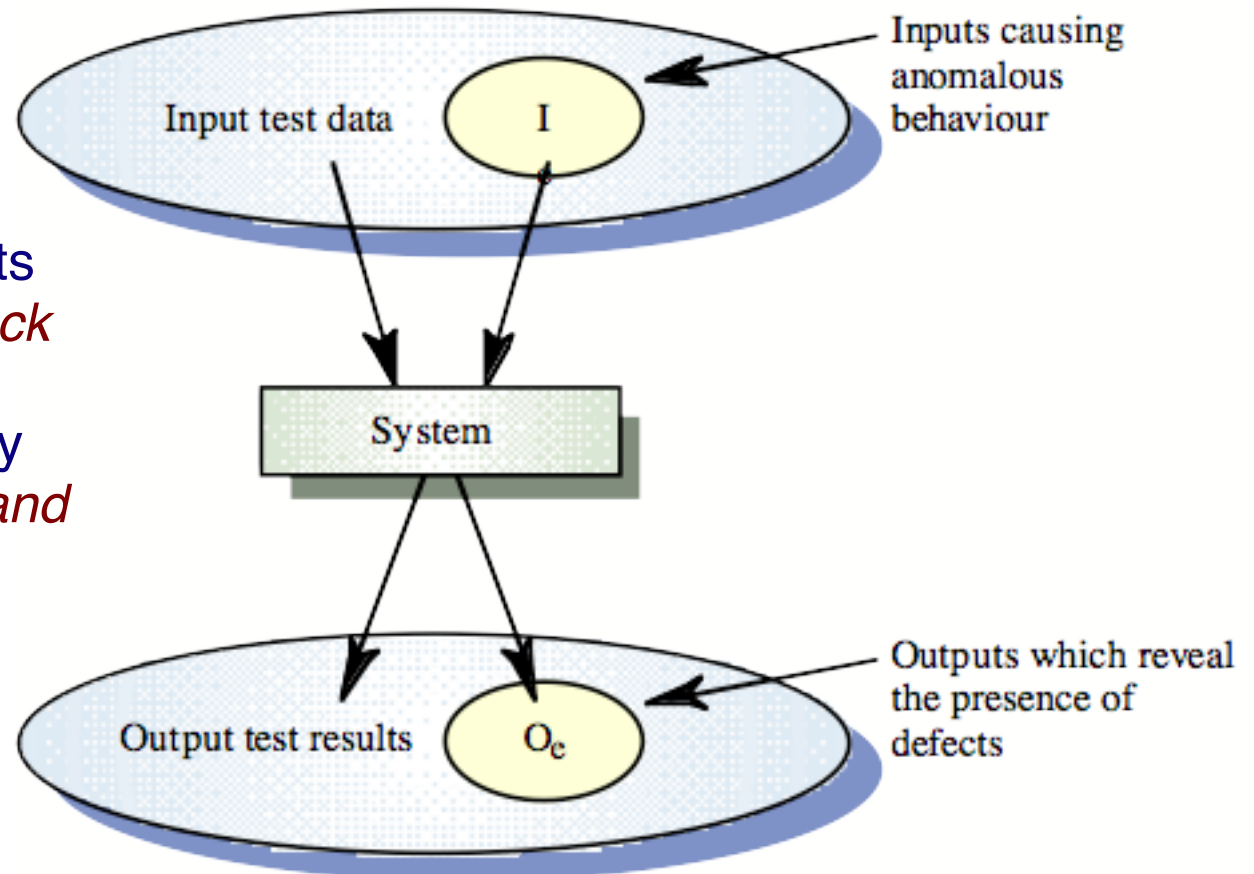
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Functional (black box) testing

Functional testing treats a component as a “*black box*” whose behaviour can be determined only by studying its *inputs and outputs*.



Coverage Criteria

Test cases are derived from the *external specification* of the component and should cover:

- > all exceptions
- > all data ranges (incl. invalid) generating different classes of output
- > all boundary values

Test cases can be derived from a component's *interface*, by assuming that the component will behave similarly for all members of an *equivalence partition* ...

Equivalence partitioning

```
public static void search(int key, int [] elemArray, Result r)
    { ... }
```

Check input partitions:

- > Do the inputs fulfil the *pre-conditions*?
 - is the array sorted, non-empty ...
- > Is the key in the array?
 - leads to (at least) 2x2 equivalence classes

Check boundary conditions:

- > Is the array of length 1?
- > Is the key at the start or end of the array?
 - leads to further subdivisions (not all combinations make sense)

Test Cases and Test Data

Generate test data that cover all *meaningful* equivalence partitions.

<i>Test Cases</i>	<i>Test Data</i>
Array length 0	key = 17, elements = { }
Array not sorted	key = 17, elements = { 33, 20, 17, 18 }
Array size 1, key in array	key = 17, elements = { 17 }
Array size 1, key not in array	key = 0, elements = { 17 }
Array size > 1, key is first element	key = 17, elements = { 17, 18, 20, 33 }
Array size > 1, key is last element	key = 33, elements = { 17, 18, 20, 33 }
Array size > 1, key is in middle	key = 20, elements = { 17, 18, 20, 33 }
Array size > 1, key not in array	key = 50, elements = { 17, 18, 20, 33 }
...	

Roadmap

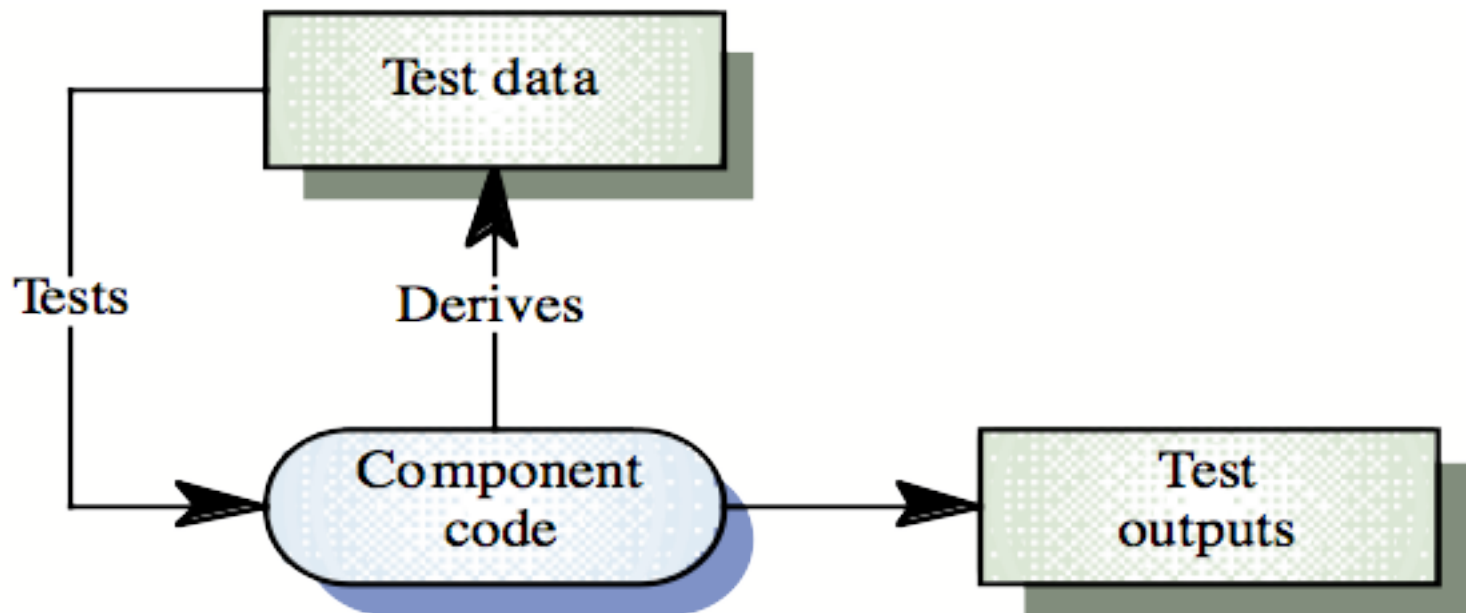
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Structural (white box) Testing

Structural testing treats a component as a “*white box*” or “glass box” whose *structure can be examined to generate test cases*.

Derive test cases to *maximize coverage* of that structure, yet *minimize the number of test cases*.



Coverage criteria

- > *every statement* at least once
- > *all portions of control flow* at least once
- > *all possible values of compound conditions* at least once
- > *all portions of data flow* at least once
- > for *all loops* L, with n allowable passes:
 - I. skip the loop;
 - II. 1 pass through the loop
 - III. 2 passes
 - IV. m passes where $2 < m < n$
 - V. n-1, n, n+1 passes

Path testing is a white-box strategy which exercises *every independent execution path* through a component.

```

class BinSearch {
// This is an encapsulation of a binary search function that takes an array of
// ordered objects and a key and returns an object with 2 attributes namely
// index - the value of the array index
// found - a boolean indicating whether or not the key is in the array
// An object is returned because it is not possible in Java to pass basic types by
// reference to a function and so return two values
// the key is -1 if the element is not found
    public static void search (int key, int [] elemArray, Result r)
    {
        int bottom = 0;
        int top = elemArray.length - 1;
        int mid;
        r.found = false; r.index = -1;
        while ( bottom <= top)
        {
            mid = (top + bottom) / 2;
            if (elemArray [mid] == key)
            {
                r.index = mid;
                r.found = true;
                return ;
            } // if part
            else
            {
                if (elemArray [mid] < key)
                {
                    bottom = mid + 1;
                }
                else
                {
                    top = mid -1;
                }
            } //while loop
        } //search
    } //BinSearch
}

```

(1)

(2)

(3)

(8)

-> (9)

(4)

(5)

(6)

(7)

(9)

Program flow graphs

- > Each branch is shown as a separate path and loops are shown by arrows looping back to the loop condition node
- > The number of tests to test all control statements equals the *cyclomatic complexity*

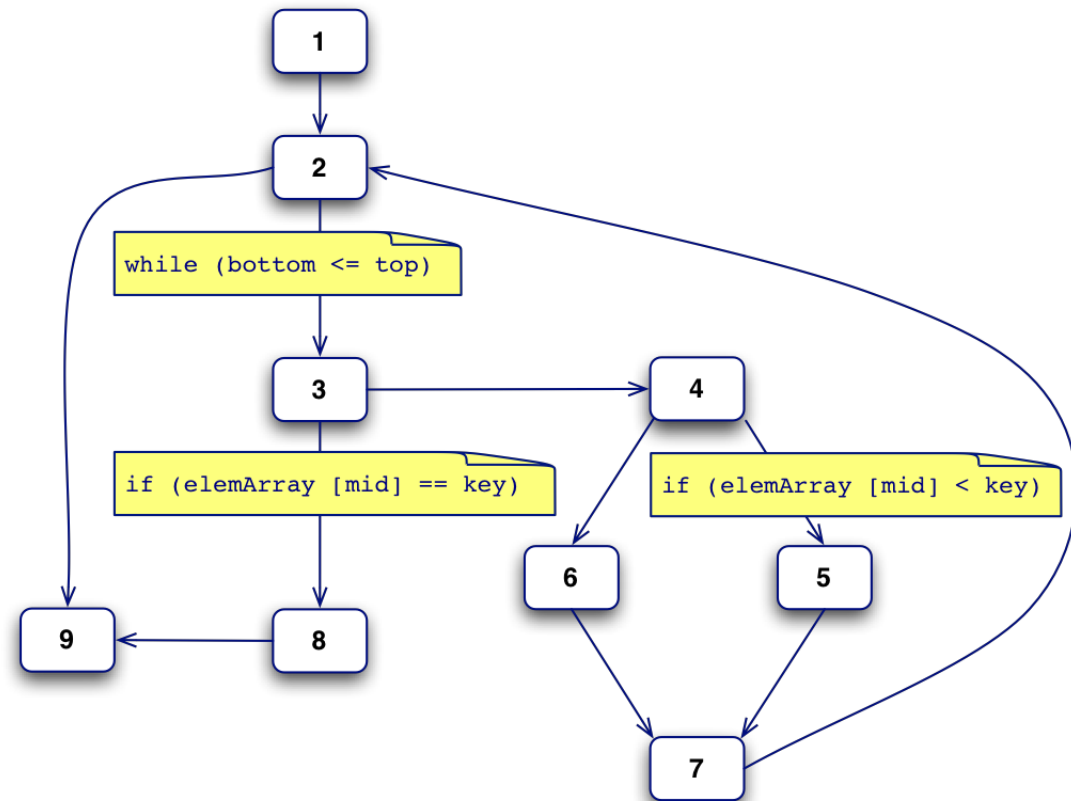
$$\text{Cyclomatic complexity} = \text{Number of edges} - \text{Number of nodes} + 2$$

Path Testing

Test cases should be chosen to cover all *independent paths* through a routine:

- 1, 2, 9
- 1, 2, 3, 8, 9
- 1, 2, 3, 4, 5, 7, 2, 9
- 1, 2, 3, 4, 6, 7, 2, 9

(Each path traverses *at least one new edge*)



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Statistical Testing

The objective of statistical testing is to determine the *reliability* of the software, rather than to discover faults.

Reliability may be expressed as:

- > *probability* of failure on demand
 - i.e., for safety-critical systems
- > *rate* of failure occurrence
 - i.e., #failures/time unit
- > *mean time* to failure
 - i.e., for a stable system
- > *availability*
 - i.e., fraction of time, for e.g. telecom systems

Statistical Testing ...

Tests are designed to reflect the *frequency of actual user inputs* and, after running the tests, an estimate of the operational reliability of the system can be made:

1. *Determine usage patterns* of the system (classes of input and probabilities)
2. *Select or generate test data* corresponding to these patterns
3. *Apply the test cases*, recording execution time to failure
4. Based on a statistically significant number of test runs, *compute reliability*

When to Stop?

When are we done testing? When do we have enough tests?

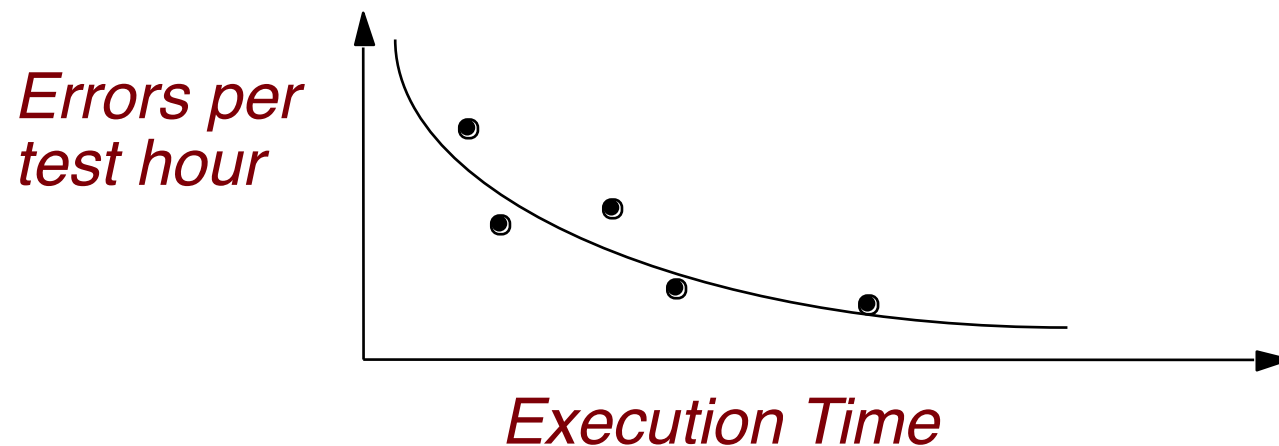
Cynical Answers (sad but true)

- > You're *never done*: each run of the system is a new test
 - Each bug-fix should be accompanied by a new regression test
- > You're done when you are out of time/money
 - Include testing in the project plan and *do not give in to pressure*
 - ... in the long run, tests save time

When to Stop? ...

Statistical Testing

- > Test until you've reduced the failure rate to fall below the risk threshold
 - Testing is like an insurance company calculating risks



What you should know!

- > What is the difference between a failure and a fault?
- > What kinds of failure classes are important?
- > How can a software system be made fault-tolerant?
- > How do assertions help to make software more reliable?
- > What are the goals of software validation and verification?
- > What is the difference between test cases and test data?
- > How can you develop test cases for your programs?
- > What is the goal of path testing?

Can you answer the following questions?

- > When would you combine top-down testing with bottom-up testing?
- > When would you combine black-box testing with white-box testing?
- > Is it acceptable to deliver a system that is not 100% reliable?

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